



Group decision-making in the shadow of disagreement

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Abstract

A model of group decision-making is studied, in which one of two alternatives must be chosen. While agents differ in their preferences over alternatives, everybody prefers agreement to disagreement. Our model is distinguished by three features: *private information* regarding valuations, differing *intensities* in preferences, and the option to declare *neutrality* to avoid disagreement. There is always an equilibrium in which the majority is more aggressive in pushing its alternative, thus enforcing their will via both numbers and voice. However, under general conditions an aggressive minority equilibrium inevitably makes an appearance, provided that the group is large enough. Such equilibria invariably display a “tyranny of the minority”: the increased aggression of the minority always outweighs their smaller number, leading to the minority outcome being implemented with larger probability than the majority alternative. We fully characterize the asymptotic behavior of this model as group size becomes large, and show that all equilibria must converge to one of three possible limit outcomes.

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1. Introduction

Group decision-making is the process by which a collective of individuals attempt to reach a required level of consensus on a given issue. One can crudely divide this process into two

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important components: the deliberation among members of the group and the aggregation of individual opinions into a single group decision. Traditionally, the literature on political economy has focused on the second component by modelling group decision-making as voting games. More recently, several authors have examined group deliberation by studying its role in aggregating private information.¹ In this paper we emphasize another important aspect of group deliberation: the role it plays in allowing group members to bargain over the final decision while avoiding disagreement.

For many group decisions, disagreement, or failure to reach a consensus, is costly for all members. There are numerous instances of such environments. A government may need to formulate a long-run response to terrorism: individuals may disagree—often vehemently—over the nature of an appropriate response, but everyone might agree that complete inaction is the worst of the options. Jury members in the process of deliberation may disagree on whether or not the defendant is guilty; however, in most cases they all prefer to reach an agreement than to drag on the deliberations endlessly. An investigative committee looking into the causes of a riot, or a political assassination, or a corruption scandal, may be under significant pressure to formulate *some* explanation, rather than simply say they do not know. Or citizens may need to agree on a constitution under the threat of civil war if such agreement cannot be reached.

When facing a threat of disagreement, groups usually try to avoid reaching this outcome by allowing its members, either formally or informally, to declare “neutrality”; effectively, to suggest that they do not care strongly about either alternative and will support any outcome that may be more forcefully espoused by others with more intense preferences. For instance, think of an academic department that meets to make an offer to one of several candidates. Different faculty members may disagree over the ranking of the candidates. To be sure, some faculty members will feel more strongly about the choices than others. However, no member wants to see the slot taken away by the Dean because the department could not agree on an offer. Because faculty members may be uncertain as to the rankings and intensities of their colleagues, those faculty members who do not feel strongly about the issue will be less vocal and willing to “go with the flow”, while those who feel strongly about their favorite candidate will argue aggressively in her favor.

Likewise, in the jury example mentioned above, members may disagree over whether or not the defendant is guilty. Moreover, some jury members would have stronger feelings about the matter than others. However, in most cases, all would want to reach *some* unanimous decision rather than end up with a hung jury.² Consequently, those jurors who feel strongly towards conviction or acquittal would be more vocal during deliberation, while those who feel less strongly on the issue might not oppose either side in order to facilitate an agreement.

A threat of disagreement has profound implications for group decision-making. Above all, preference intensities play a critical role: the decisions of individuals within the group are based not only on their *ordinal* ranking of the available alternatives, but also on how *strongly*

¹ See Gerardi and Yariv [10], Austen-Smith and Federsen [2] and Coughlan [7].

² A case in point is the recent trial of Lee Malvo, the younger of the two men accused in the D.C. sniper case. According to the interviews conducted with some of the jury members who sat on that trial, the jury was split between conviction and acquittal. Even though conviction could mean the death penalty for the accused, some of the jurors who opposed conviction remarked that they felt it was more important to reach a unanimous decision than end up with a hung jury (New York Times, [21]).

they feel towards each one. With cardinal preferences central to our discourse, it is possible to address several important questions left unanswered in the literature. Do individuals, who favor an outcome which is less likely to be favored by the majority, fight more aggressively for their cause than individuals who hold the majority view? Can such aggression be strong enough so that the minority alternative is indeed implemented with greater probability than the outcome favored by the majority? Do higher levels of required consensus better protect the implementation of such minority outcomes? What is the likelihood that group deliberation will end in disagreement? To answer these and other related questions, we propose a simple and tractable model of group decision-making in the shadow of disagreement. We proceed as follows.

A group of n agents must make a joint choice from a set of two alternatives, A or B . Each agent must either announce an alternative— A or B —or she can declare “neutrality”, in that she agrees to be counted, in principle, for either side. Once this is accomplished, we tally declarations for each alternative, *including the number of neutral announcements*. If, for an alternative, the resulting total is no less than some exogenously given supermajority, we shall call that alternative *eligible*.

Because neutral announcements are allowed for and counted on both sides, all sorts of combinations are possible: exactly one alternative may be eligible, or neither, or both. If *exactly* one alternative is eligible, that alternative is implemented. If neither is eligible—which will happen if there is a fierce battle to protect one’s favorite alternative—then no alternative is picked: the outcome is disagreement. If both are eligible—as will typically be the case when there are a large number of neutrals—each alternative is equally likely to be implemented.

Our objective is to capture the basic strategic considerations common to several situations in which disagreement is costly. In this sense the model is sparse but inclusive: disagreement (or the threat of it) is at center stage, there is preference heterogeneity—in the ordinal sense of course, but in a cardinal sense as well, and there is the possibility of avoiding disagreement by means of capitulation. We therefore believe that by analyzing the equilibria of this model, we can gain important insights into a wide variety of situations.

Several specific features of the model deserve comment. First, while the language of a voting model is often used, we do not necessarily have voting in mind. The exogenously given supermajority may or may not amount to full consensus or unanimity, and in any case is to be interpreted as some preassigned degree of consensus or social norm that the group needs to achieve. For instance, in many informal situations, it may be considered socially undesirable to choose an option objected to by at least one person.

Second, relative to existing literature the option to remain neutral is a novel feature of our model. At the same time, it is a natural ingredient in the examples discussed above. We only add here that the neutrality option may be interpreted in several ways. One formal institution that is related is approval voting: members of the group submit an “approval” or “disapproval” for each alternative. A voter who approves both alternatives is effectively declaring neutrality. Or consider group debate that effectively proceeds like a war of attrition: members who drop out are in essence declaring neutrality. In addition, we have already discussed several examples in which neutrality is an informal yet central feature of the decision-making process. One could also imagine several quasi-formal mechanisms that help individuals to avoid disagreement by allowing their vote to be counted in a way that ensures a win to one of the alternatives. For example, one could delegate his ballot to an impartial arbitrator, who appreciates the anxiety of all concerned to avoid disagreement, and is therefore interested in implementing some outcome. In short, one could interpret the neutrality declaration as the reduced form of some unspecified procedure, which is used to help avoid unnecessary disagreements.

Third, in the model eligibility is a “zero-one” characteristic: either an alternative is eligible or it is not. Any outcome that passes the test of garnering the support (either actively by declaring the alternative, or passively by declaring neutrality) of the required supermajority, is deemed socially fit—or eligible—to be implemented. There is no sense in which one alternative is “more eligible” than another. Hence, if both alternatives are eligible, then both are on equal footing in terms of the social approval received. We therefore assume that the group implements each of the alternatives with equal probability.

To be sure, the particular tie-breaking rule used by a group may vary across different situations. In some situations, the group may vote again and again until only one outcome becomes eligible. In other situations, group members may bargain over which outcome to implement. There may be also situations in which the group would simply choose the eligible outcome with the most votes. Or an arbitrator or committee chair may break ties. The advantage of our approach is that it greatly simplifies the analysis and allows us to provide a full characterization of the equilibria. Sections 7.1 and 7.2 discusses some of the implications of assuming an alternative tie-breaking rule.

Finally, we are interested in the “intensity” of preferences for one alternative over the other, and how this enters into the decision to be neutral, or to fight for one’s favorite outcome. Specifically, we permit each person’s valuations to be independent (and private) draws from a distribution, and allow quite generally for varying cardinal degrees of preference. A corollary of this formulation is that *others* are not quite sure of how strongly a particular individual might feel about an outcome and therefore about how that individual might behave. This is one way in which uncertainty enters the model.

Uncertainty plays an additional role, in that no one is sure how many people favor one given alternative over the other. We do suppose, however, that there is a common prior—represented by an independent probability p —that an individual will (ordinally) favor one alternative (call it A) over the other (call it B). Without loss of generality take $p \leq \frac{1}{2}$. If, in fact, $p < \frac{1}{2}$, one might say that it is commonly known that people of “type A ” are in a minority, or more precisely in a *stochastic* minority. We shall see that these two types of uncertainty are very important for the results we obtain.

We provide a full characterization of this model and study a number of extensions and variations. Our main results highlight the important implications of a threat of disagreement.

Cardinal preferences play a key role. In any equilibrium, each individual employs a cutoff rule: there will exist some critical relative intensity of preference (for one alternative over the other) such that the individual will announce her favorite outcome if intensities exceed this threshold, and neutrality otherwise. If a rule exhibits a lower cutoff, then an individual using that rule may be viewed as being more “aggressive”: she announces her own favorite outcome more easily, and risks disagreement with greater probability.

Equilibria in which an individual of the majority type uses a lower cutoff (and is therefore more aggressive) than her minority counterpart may be viewed as favoring the majority: we call them *majority equilibria*. Likewise, equilibria in which the minority type employs a lower cutoff will be called *minority equilibria*.

Using an obvious parallel from the Battle of the Sexes, there are always “corner” equilibria in which one side is “infinitely” aggressive—i.e., uses the lowest cutoff—while the other side is cowed into declaring full neutrality. But the resemblance ends there. In the model we study, a simple and weak robustness criterion reveals such equilibria to be particularly fragile. Section 4.2.2 introduces the refinement and shows how it removes corner equilibria in which one side invariably gives up.

Majority equilibria always exist. There always exists an equilibrium in which the majority uses a more aggressive cutoff than the minority (Proposition 1). This is an interesting manifestation of the “tyranny of the majority”.³ Not only are the majority greater in number (or at least stochastically so), they are also more vocal in expressing their opinion. In response—and fearing disagreement—the minority are more cowed towards neutrality. So in majority equilibrium, group outcomes are doubly shifted towards the majority view, once through numbers, and once through greater voice.

Minority equilibria exist for large group sizes. Proposition 2 establishes the following result: if the required supermajority μ is not unanimity (i.e., $\mu < 1$), and if the size of the stochastic minority p exceeds $1 - \mu$, then for all sufficiently large population sizes, a minority equilibrium must exist.

How large is large? To be sure, the answer must depend on the specifics of the model, but our computations suggest that in reasonable cases, population sizes of 8–10 (certainly less than the size of a jury!) are enough for existence. We interpret this to mean that our existence result not only applies to large populations, but also to committees, juries, academic departments, cabinets and other groups which are numbered in the tens rather than in the hundreds.

From one point of view this result seems intuitive, yet from others it is remarkable. Intuitively, as population size increases, the two types of uncertainty that we described—uncertainty about type and uncertainty regarding valuation intensity—tend to diminish under the strength of the Law of Large Numbers. This would do no good if $p < 1 - \mu$, for then the minority would neither be able to win, nor would it be able to block the majority. (Indeed, Proposition 3 in Section 5.2 shows that if $p < 1 - \mu$, then for large population sizes a minority equilibrium cannot exist.) But if p exceeds $1 - \mu$, the minority acquires the “credibility” to block the wishes of the majority, or at least does so when the population is large enough.

The existence of minority equilibria is not monotone in the consensus level. For two reasons, however, the above notion of “credible blocking” does not form a complete explanation. First, a credible block is not tantamount to a credible *win*. Indeed, it is easy to see that as μ goes up, the minority find it easier to block but also harder to win. So the previous result must *not* be viewed as an assertion that the minority is “better protected” by an increase in μ . Indeed, as an example in Section 5.1 makes clear, this is not true. (Nevertheless, insofar as existence is concerned, the fact that $p > 1 - \mu > 0$ guarantees existence of minority equilibrium for large population sizes.)

Second—and this extends further the line of argument in the previous paragraph—the case of unanimity ($\mu = 0$) is special. Proposition 4 shows that there are conditions (on the distribution of valuations) under which a minority equilibrium *never* exists, no matter how large the population size is. So blocking credibility alone does not translate into the existence of a minority equilibrium in the unanimity case. In short, any “intuitive explanation” for Proposition 2 must also account for these observations.

The minority win more often in a minority equilibrium. Recall that in a majority equilibrium, the majority will have a greater chance of implementing its preferred outcome on two counts: greater voice, and greater number. Obviously, this synergy is reversed for the minority equilibrium: there, the minority have greater voice, yet they have smaller numbers. One might expect the net effect of these two forces to result in some ambiguity. The intriguing content of Proposition 5 is that in a minority equilibrium, the minority must always implement its favorite action with

³ It is possible that our use of this term constitutes a slight abuse of terminology, given that the phrase is typically invoked in the context of simple majority rule. We deal with supermajorities, so the term “tyranny” (of either majority or minority) here is used in the sense of more strident use of *voice*.

greater probability than the majority. Whenever a minority equilibrium exists, voice more than compensates for number.

Even in large groups, both sides may put up a fight. All equilibrium sequences must have limit points that are one of these three. Two of the outcomes may be viewed as “limit minority equilibria”. One of them exhibits a zero cutoff for the minority, and the other exhibits a positive minority cutoff which is nevertheless lower than the majority cutoff. The third outcome is a “limit majority equilibrium” in which the cutoff used by the majority is zero. The striking feature of these outcomes is that under some conditions, neither side gives up even if the opposition uses a zero cutoff! In particular, we establish the necessary and sufficient conditions for the existence of these interior cutoffs and describe exactly what they are.

Even as group size grows large, agreement is reached with uniformly positive probability. Given that both sides may put up a fight in relatively large groups, one might expect that for sufficiently high supermajority requirements disagreement will be endemic. However, for all non-unanimity rules, the probability of disagreement not only stays away from one, but actually converges to zero along any equilibrium sequences which converges to a limit outcome in which one side uses a zero cutoff. For those equilibria that converge to the remaining minority outcome, we show that the probability of disagreement is bounded away from one even as the population size goes to infinity.

Our results show that a “shadow of disagreement” may effectively induce groups to make decisions that take into account their members’ preference intensities. In particular, individuals who support an outcome that is less likely (ex-ante) to be favored by the majority, may still be able to implement that outcome if they feel sufficiently strongly about it. However, our paper also suggests that in group decision-making the outcomes tend to be invariably biased in one direction or another. In majority equilibrium this is obvious. But it is also true of minority equilibrium. This lends some support to a commonly-held view that group decision-making tends to have some degree of extremism built into the process.⁴

2. Related literature

One central result in our paper is that minorities may fight more aggressively and win. Of course, the well-known Pareto–Olson thesis (see [24,22]) suggests that minorities might put up a stronger fight when voting is costly. This intuition is confirmed in some complete-information models with private voting costs (see [1,13]), though in other variants with incomplete information (e.g., [23,18,4,16,12]), the majority still wins at least as frequently as the minority even when the minority fights harder, assuming that preference intensities do not differ across groups.⁵

Our model also features a “cost of voting”: it is the expected loss caused by disagreement. But this cost is a *public* bad, and it cannot be shifted from one voter to another. (In addition, the magnitude of this cost is determined endogenously in equilibrium.)

An important feature of our model is that individuals base their decision on how strongly they prefer one alternative to another. This feature is shared with several papers that investigate different mechanisms in which intensity of preferences determine individual voting behavior. Vote-trading

⁴ The phenomenon of “group polarization” has been extensively studied in the social psychology literature, most notably in [20,17]. A more recent experimental study of this phenomenon is [6]. In the political science and law literature, the potential impact of group polarization on court decisions has been studied by Sunstein [28–30].

⁵ Certainly, if minorities are sufficiently more zealous in the espousal of their favorite issue, they may fight more aggressively and win more often, as [4] also shows.

mechanisms, in which voters can trade their votes with one another, have been analyzed in [3] and have more recently been revisited by Philipson and Snyder [25] and Piketty [26]. Cumulative voting mechanisms in which each voter may allocate a fixed number of votes among a set of candidates has been analyzed as early as in [8] and more recently revisited by Gerber et al. [11], Jackson and Sonnenschein [15] and Hortala-Vallve [14]. In a related vein, Casella [5] introduces a system of storable votes, in which voters can choose to store votes in order to use them in situations that they feel more strongly about.

These papers take a normative approach to group decision making in an attempt to design optimal procedures. Our approach is different. We take a positive approach and focus on existing institutions that rely on supermajority rules. We argue that a threat of disagreement may push individuals to base their decisions not only on their ordinal preferences, but also on their preference intensities. At the same time, we do not claim that the decision protocol we analyze—a supermajority rule coupled with a neutrality option and a threat of disagreement—necessarily leads to an efficient outcome (though mechanism design in our context would certainly be an interesting research project).

In particular, our analysis highlights the importance of consensus and the fear of gridlock as a mechanism through which intensities of preferences are translated into the decision making process. In this context, Ponsati and Sákovicz [27] is also related to the present paper. Indeed, their model is more ambitious in that they explicitly attempt to study the dynamics of capitulation in an ambient environment similar to that studied here. This leads to a variant on the war of attrition, and their goal is to describe equilibria as differential equations for capitulation times, at which individuals cease to push their favorite alternative.

3. The Model

3.1. The group choice problem

A group of n agents must make a joint choice from a set of two alternatives, which we denote by A and B . The rules of choice are described as follows:

- (1) Each agent must either name an alternative— A or B —or she can declare “neutrality”, in that she agrees to be counted, in principle, for either side.
- (2) If the total number of votes for an alternative plus the number of neutral votes is no less than some exogenously given supermajority m ($> n/2$), then we shall call that alternative *eligible*.
- (3) If no alternative is eligible, no alternative is chosen: a state D (for “disagreement”) is the outcome.
- (4) If a single alternative is eligible, then that alternative is chosen.
- (5) If *both* alternatives are eligible, A or B are chosen with equal probability.

Recall that our tie-breaking rule follows from our view of eligibility as a “zero-one” characteristic: either an alternative is eligible or it is not, so that there is no sense in which one alternative is “more eligible” than another. The point is simply this: if no alternative is blocked, it matters little whether one alternative gets more votes than another—the preassigned degree of consensus (or at least the lack of opposition) has been achieved for both alternatives. This is not to suggest, however, that other tie-breaking rules are not worth exploring. An obvious contender is one in which the option with the most votes wins in case both pass the supermajority requirement. We discuss the implication of using this alternative tie-breaking rule in Section 7.2.

3.2. Valuations

Normalizing the value of disagreement to zero, each individual will have valuations (v_A, v_B) over A and B . These valuations are random variables, and we assume they are private information. Use the notation (v, v') , where v is the valuation of the favorite outcome ($\max\{v_A, v_B\}$), and v' is the valuation of the remaining outcome ($\min\{v_A, v_B\}$). An individual will be said to be of *type A* if $v = v(A)$, and of *type B* if $v = v_B$. (The case $v_A = v_B$ is unimportant as we will rule out mass points below.)

Our first restriction is

(A.1) Each individual prefers either outcome to disagreement. That is, $(v, v') \gg 0$ with probability one.

In Section 7.5 we remark on the consequences of dropping the assumption that disagreement is worse than either alternative.

In what follows we shall impose perfect symmetry across the two types *except* for the probability of being one type or the other, which we permit to depart from $\frac{1}{2}$. (The whole idea, after all, is to study majorities and minorities.)

(A.2) A person is type A with (iid) probability $p \in (0, \frac{1}{2}]$, and is type B otherwise. Regardless of specific type, however, (v, v') are chosen independently and identically across agents.

3.3. The game

First, each player is (privately) informed of her valuation (v_A, v_B) . Conditional on this information she decides to announce either A or B , or simply remain neutral and agree to be counted in any direction that facilitates agreement. Because an announcement of the less-favored alternative alone is weakly dominated by a neutral stance, we presume that each player either decides to announce her own type, or to be neutral.⁶ The rules in Section 2.1 then determine expected payoffs.

4. Equilibrium

4.1. Cutoffs

We reiterate, for clarity in what follows, that when we say a player “announces an outcome”, we mean that *only* that alternative is named by the player; she has forsaken neutrality.

Consider a player of a particular type, with valuations (v, v') . Define $q \equiv n - m$. Notice that our player only has an effect on the outcome of the game—that is, she is pivotal—in the event that there are *exactly* q other players announcing her favorite outcome. For suppose there are more than q such announcements, say for A . Then B cannot be eligible, and whether or not A is eligible, our player’s announcement cannot change this fact. So our player has no effect on the outcome. Likewise, if there are strictly less than q announcements of A , then B is eligible whether or not A is, and our player’s vote (A or neutral) cannot change the status of the latter.

Now look at the pivotal events more closely. One case is when there are precisely q announcements in favor of A , and $q + 1$ or more announcements favoring B . In this case, by staying neutral our agent ensures that B is the only eligible outcome and is therefore chosen. By announcing A

⁶ For a similar reason we need not include the possibility of abstention. Abstention (as opposed to neutrality) simply increases the probability of disagreement, which all players dislike by assumption.

she guarantees that neither outcome is eligible, so disagreement ensues. In short, by switching her announcement from neutral to A , our agent creates a personal loss of v' .

In the second case, there are q announcements or less in favor of B . In this case, by going neutral our agent ensures that A and B are both eligible, so the outcome is an equiprobable choice of either A or B . On the other hand, by announcing A , our agent guarantees that A is the *only* eligible outcome. Therefore by switching in this instance from neutral to announcing A , our agent creates a personal gain of $v - (v + v')/2$.

To summarize, let P^+ denote the probability of the former pivotal event (q compatriots announcing A , $q + 1$ or more announcing B) and P^- the probability of the latter pivotal event (q compatriots announcing A , q or less announcing B). It must be emphasized that these probabilities are not exogenous. They depend on several factors, but most critically on the strategies followed by the other agents in the group. Very soon we shall look at this dependence more closely, but notice that even at this preliminary stage we can see that our agent must follow a *cutoff rule*. For announcing A is weakly preferred to neutrality if and only if

$$P^- [v - (v + v')/2] \geq P^+ v'.$$

Define $u \equiv \frac{v - (v + v')/2}{v'}$. Note that (by (A.1)) u is a well-defined random variable. Then the condition above reduces to

$$P^- u \geq P^+, \tag{1}$$

which immediately shows that our agent will follow a cutoff rule using the variable u .

Notice that we include the extreme rules of always announcing neutrality (or always announcing one's favorite action) in the family of cutoff rules. (Simply think of u as a nonnegative extended real.) If a cutoff rule does not conform to one of these two extremes, we shall say that it is *interior*.

By (A.2), the variable u has the same distribution no matter which type we are referring to. We assume

(A.3) u is distributed according to the atomless cdf F , with strictly positive density f on $(0, \infty)$.

4.2. Symmetric equilibrium

In this paper, we study symmetric equilibria: those in which individuals of the same type employ identical cutoffs.

4.2.1. Symmetric cutoffs

Assume, then, that all A -types use the cutoff u_A and all B -types use the cutoff u_B . We can now construct the probability that a *randomly chosen* individual will announce A : she must be of type A , which happens with probability p , and she must want to announce A , which happens with probability $1 - F(u_A)$. Therefore the overall probability of announcing A , which we denote by λ_A , is given by

$$\lambda_A \equiv p[1 - F(u_A)].$$

Similarly, the probability that a randomly chosen individual will announce B is given by

$$\lambda_B \equiv (1 - p)[1 - F(u_B)].$$

With this notation in hand, we can rewrite the cutoff rule (1) more explicitly. First, add P^- to both sides to get

$$P^-(1 + u) \geq P^+ + P^-.$$

Assuming that we are studying this inequality for a person of type A , the right-hand side is the probability that exactly q individuals announce A , while the term P^- on the left-hand side is the joint probability that exactly q individuals announce A and no more than q individuals announce B . With this in mind, we see that the cutoff u_A must solve the equation

$$\begin{aligned} & \binom{n-1}{q} \lambda_A^q \sum_{k=0}^q \binom{n-1-q}{k} \lambda_B^k (1 - \lambda_A - \lambda_B)^{n-1-q-k} (1 + u_A) \\ &= \binom{n-1}{q} \lambda_A^q (1 - \lambda_A)^{n-1-q}. \end{aligned} \tag{2}$$

Likewise, the cutoff u_B solves

$$\begin{aligned} & \binom{n-1}{q} \lambda_B^q \sum_{k=0}^q \binom{n-1-q}{k} \lambda_A^k (1 - \lambda_A - \lambda_B)^{n-1-q-k} (1 + u_B) \\ &= \binom{n-1}{q} \lambda_B^q (1 - \lambda_B)^{n-1-q}. \end{aligned} \tag{3}$$

We will sometimes refer to these cutoffs as “equilibrium responses”, to emphasize the fact that u_A embodies not just a “best response” by an individual but is also an “equilibrium condition” among individuals of the same type, given the cutoff used by the other type. The term “equilibrium response” captures the hybrid nature of the group response.

4.2.2. A refinement for equilibrium responses

At this stage, an issue arises which we would do well to deal with immediately. It is that a symmetric cutoff of ∞ is always an equilibrium response for any type to any cutoff employed by the other type, provided that $q > 0$. This is easy enough to check: if no member in group A is prepared to declare A in any circumstance, then no individual in that group will find it in her interest to do so either. This is because (with $q > 0$) no such individual is ever pivotal.

Hence the “full neutrality cutoff” $u = \infty$ is always an equilibrium response. But it is an unsatisfactory equilibrium response for the following reason. Fix a particular person, say of type A . Perturb the strategy of her compatriots from full neutrality to one in which they do announce A for a tiny range of very high u -values. Below, we demonstrate that this will make our person announce A for all but a bounded range of u -values, where the bound on this range is independent of the perturbation to the compatriots.

Before we show this, let us distill a formal requirement from the discussion above. Focus on the A -types with domain variable u . To handle infinite cutoffs, define the variable $w \equiv u/(1 + u)$; obviously, the cutoffs with respect to u translate directly into cutoffs with respect to w . In particular, full neutrality is just a cutoff of 1 in w -space. Now suppose that a (symmetric) cutoff w^* is an equilibrium response to some cutoff used by the other type. We will say that such a cutoff is *fragile* if there exists $\varepsilon > 0$ such that if w is the cutoff used instead of w^* , an individual member of the group will prefer to use a cutoff that is at least ε -far from w^* , no matter how close w is to w^* .

Observe that this criterion is much weaker than “tatonnement style” refinements which would examine whether a response close to the putative equilibrium would lead to a sequence of “myopic”

best responses away from the original response. Our criterion raises a red flag only when there is a *discontinuous jump* from the original actions following an arbitrarily small perturbation—this is the significance of the requirement that ε is uniform in the perturbation. If our criterion is violated, the equilibrium response under scrutiny fails—in a strong sense—to be robust: the tiniest mistakes by others will drive an individual “far away” from the prescribed action.

It turns out that this criterion eliminates—and *only* eliminates—those equilibrium responses exhibiting full neutrality.

Observation 1. *An equilibrium response is fragile if and only if it is infinite (in u -space, equivalently equal to 1 in w -space).*

Half this observation is obvious. Look at (2), which determines the cutoff u_A for a member of type A , as a function of λ_B (which is determined by the cutoff of the other type and so is fixed for the discussion) and of λ_A (which is determined by the cutoff employed by the A -compatriots). If the equilibrium response in question is finite, then $\lambda_A > 0$, and u_A is uniquely defined and moves continuously in λ_A , so that the question of fragility does not arise.

Indeed, in all the cases in which $\lambda_A > 0$, (2) reduces to the simpler form

$$\sum_{k=0}^q \binom{n-1-q}{k} \lambda_B^k (1-\lambda_A-\lambda_B)^{n-1-q-k} (1+u'_A) = (1-\lambda_A)^{n-1-q}. \tag{4}$$

where we are denoting our individual’s cutoff by u'_A as a reminder that we have not imposed the symmetry condition yet. Notice that this value of u'_A is uniformly bounded, say, by some number $M < \infty$ no matter what values λ_A and λ_B assume, even if λ_A approaches zero. This is the source of the fragility of full-neutrality: when $\lambda_A = 0$, so that all compatriots employ an infinite cutoff, then $u_A = \infty$ is a solution, but this cutoff jumps to no more than M as soon as there is any perturbation to a positive value of λ_a .

Intuitively, consider an individual of type A , and entertain a small perturbation in the fully neutral strategy of her compatriots: they now use a very large cutoff, but not an infinite one. Now, in the event that our agent is pivotal, it must be that her group is very large with high probability, because her compatriots are only participating to a tiny extent, and yet there are q participants in the pivotal case. This means that group A is likely to win (conditional on the pivotal event), and our individual will want to declare A for all but a uniformly bounded range of her u -values.

Note that in the special case of unanimity ($q = 0$), full neutrality is *never* an equilibrium response, so no refinements need to be invoked.

Finally, it should be noted that weak dominance is not enough to rule out full neutrality. To see this consider the profile in which both groups use a cutoff of zero and so are always voting their type. In this case, when a voter of type A is pivotal, he knows for sure that there are more than q declarations of B . Therefore, this voter has a strict incentive to claim neutrality. Note however, that the above profile is the only profile against which neutrality is a strict equilibrium response for *every* type.

4.2.3. Equilibrium conditions

In summary, then, the arguments of the previous section permit us to rewrite the equilibrium conditions (2) and (3) as follows:

$$\alpha(u_A, u_B) \equiv (1+u_A) \sum_{k=0}^q \binom{m-1}{k} \pi^k (1-\pi)^{m-1-k} = 1 \tag{5}$$

and

$$\beta(u_A, u_B) \equiv (1 + u_B) \sum_{k=0}^q \binom{m-1}{k} \sigma^k (1 - \sigma)^{m-1-k} = 1, \tag{6}$$

where $m = n - q$, $\pi \equiv \lambda_B/1 - \lambda_A$, and $\sigma \equiv \lambda_A/1 - \lambda_B$.

We dispose immediately of a simple subcase: the situation in which there is simple majority and n is odd, so that q precisely equals $(n - 1)/2$. The following result applies:

Observation 2. *If $q = (n - 1)/2$, there is a unique equilibrium which involves $u_A = u_B = 0$.*

To see why this must be true, consult (5) and (6). Notice that when $q = (n - 1)/2$, it must be that $m - 1 = n - q - 1 = q$. So an equilibrium response must equal zero no matter what the size of the other group’s cutoff. In words, there is no cost to announcing one’s favorite outcome in this case. Recall that the only conceivable cost to doing so is that disagreement might result, but in the pivotal case of concern to any player, there are q compatriots announcing the favorite outcome, which means there are no more than $n - 1 - q = q$ opposing announcements. So disagreement is not a possibility.

In the remainder of the paper, then, we concentrate on the case in which a genuine supermajority is called for:

$$(A.4) \quad q < (n - 1)/2.$$

The following observations describe the structure of response functions in this situation. (A.1)–(A.4) hold throughout.

Observation 3. *A symmetric response u_i is uniquely defined for each u_j , and declines continuously as u_j increases, beginning at some positive finite value when $u_j = 0$, and falling to zero as $u_j \rightarrow \infty$.*

Observation 4. *Consider the point at which type A’s response crosses the 45° line, or more formally, the value \bar{u} at which $\alpha(\bar{u}, \bar{u}) = 1$. Then type B’s equilibrium response cutoff to \bar{u} is lower than \bar{u} , strictly so if $p < \frac{1}{2}$.*

While the detailed computations that support these observations are relegated to Section 9, a few points are to be noted. First, complete neutrality is not an equilibrium response (it is fragile) even when members of the other group are *always* announcing their favorite alternative. The argument for this is closely related to the remarks made in Section 4.2.2 and we shall not repeat them here. On the other hand, “full aggression”— $u = 0$ —is *also* never an equilibrium response except in the limiting case as the other side tends to complete neutrality. These properties guarantee that every equilibrium (barring those excluded in Section 4.2.2) employs interior cutoffs.

Observation 4 requires some elaboration. It states that *at the point where the equilibrium response of Group A leaves both sides equally aggressive* (so that $u_A = u_B = \bar{u}$), group B’s equilibrium response leads to greater aggression. The majority takes greater comfort from its greater number, and therefore are more secure about being aggressive. There is less scope for disagreement. However, note the emphasized qualification above. As we shall see later, it will turn out to be important.

Fig. 1 provides a graphical representation. Each response function satisfies observation 3, and in addition observation 4 tells us that the response function for A lies above that for B at the 45° line. We have therefore established the following proposition.

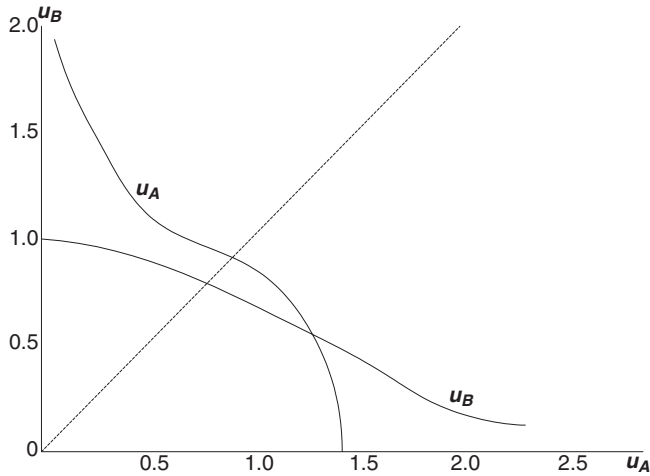


Fig. 1. Existence of a majority equilibrium.

Proposition 1. *An equilibrium exists in which members of the stochastic majority—group B—behave more aggressively than their minority counterparts: $u_B < u_A$.*

Proposition 1 captures an interesting aspect of the “tyranny of the majority”. Not only are the majority greater in number (at least stochastically so in this case), they are also more vocal in expressing their opinion. So group outcomes are doubly shifted—in this particular equilibrium—towards the majority view, once through numbers, and once through greater voice.⁷ We will call such an equilibrium a *majority equilibrium*.

5. Minority equilibria

5.1. Existence

Fig. 1, which we used in establishing Proposition 1, is drawn from actual computation. We set $n = 4$, $p = 0.4$, $q = 1/4$, and chose F to be gamma with parameters (3,4). Under this specification, there is, indeed, a unique equilibrium and (by Proposition 1) it must be the majority equilibrium.

Further experimentation with these parameters leads to an interesting outcome. When n is increased (along with q , to keep the ratio q/n constant), the response curves appear to “bend back” and intersect yet again, this time above the 45° line (see Fig. 2). A *minority equilibrium* (in which $u_A < u_B$, so that the minority are more aggressive) makes its appearance. For this example, it does so when there are 12 players.

The bending-back of response curves to generate a minority equilibrium appeared endemic enough in the computations, that we decided to probe further. To do this, we study large populations in which the ratio of q to n is held fixed at $v \in (0, \frac{1}{2})$. More precisely, we look at sequences $\{n, q\}$

⁷ Notice that this model has no voting costs so that free-riding is not an issue. Such free-riding is at the heart of the famous Olson paradox (see [22]), in which small groups may be more effective than their larger counterparts.

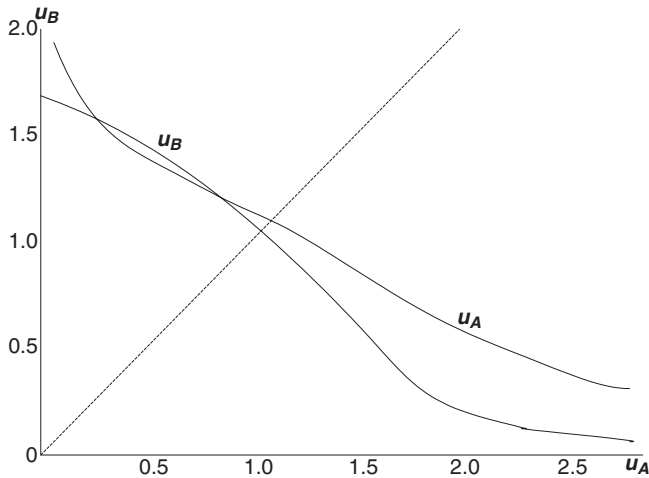


Fig. 2. Minority equilibrium.

growing unboundedly large so that q is one of the (at most) two integers closest to vn . We obtain the following analytical confirmation of the simulations:

Proposition 2. *Assume that $0 < v < p \leq \frac{1}{2}$. Consider any sequence $\{n, q\}$ such that $n \rightarrow \infty$ and q is one of the (at most) two integers closest to vn . Then there exists a finite N such that for all $n \geq N$, a minority equilibrium must exist.*

Several comments are in order. First, if there is a minority equilibrium, there must be at least two of them, because of the end point restrictions implied by Observations 3 and 4. Some of these equilibria will suffer from stability concerns similar to those discussed in Section 4.2.2. But there will always be other minority equilibria that are “robust” in this sense.⁸

Second, it might be felt that the threshold N described in Proposition 2 may be too large for “reasonable” group sizes. Our simulations reveal that this is not true. For instance, within the exponential class of valuation distributions, the threshold at which a minority equilibrium appears is typically around $N=10$ or thereabouts, which is by no means a large number.

Third, the qualification that $v > 0$ is important. The unanimity case, with $q=0$ is delicate. We return to this issue in Section 7. The case $p \leq v$, which we also treat in the next subsection, is of interest as well.

Finally, as an aside, note that Proposition 2 covers the symmetric case $p = \frac{1}{2}$, in which case the content of the proposition is that an asymmetric equilibrium exists (for large n). To be sure, the proposition is far stronger than this assertion, which would only imply (by continuity) that a minority equilibrium exists (with large n) if p is sufficiently close to $\frac{1}{2}$.

5.2. Discussion of the existence result

We can provide some intuition as to why minority existence is guaranteed for large n but not so for small n . Observe that when n is “small”, there are two sorts of uncertainties that plague

⁸ Once again, this follows from the end-point restrictions.

any player. She does not know how many people there are of her type, and she is uncertain about the realized distribution of valuations. Both these uncertainties are troublesome in that they may precipitate costly disagreement. The possibility of disagreement is lowered by more and more people adopting a neutral stance, though after a point it will be lowered sufficiently so that it pays individuals to step in and announce their favorite outcome. For a member of the stochastic majority, this point will be reached earlier, and so a majority equilibrium will always exist.

On the other hand, when n is large, these uncertainties go away or at any rate are reduced. Now the expectation that the minority will be aggressive can be credibly self-fulfilling, because the expectation of an aggressive strategy can be more readily transformed into the expectation of a winning outcome. This intuition suggests that when the proportion of the minority is smaller than the superminority ratio, then minority equilibria do not exist for large n . This is confirmed in the following proposition.

Proposition 3. *Assume that $0 < p < v < \frac{1}{2}$. Consider any sequence $\{n, q\}$ such that $n \rightarrow \infty$ and q is one of the (at most) two integers closest to vn . Then there exists a finite N such that for all $n \geq N$, a minority equilibrium does not exist.*

Taken together, Propositions 2 and 3 may suggest a monotonic relation between the supermajority requirement and the “power” of the minority. Common intuition suggests that a higher supermajority requirement facilitates the emergence of a minority equilibrium. Indeed, the comparative politics literature compares different political systems and motivates what has been termed “consensus systems” [19] by the desire to protect minorities from the tyranny of the majority.

However, this is generally false in our model. To see why, consider an individual of type A and her best response condition. As q decreases, A ’s cutoff increases (holding B ’s cutoff fixed), i.e., the group fights less aggressively. This follows from the fact that as q decreases, the probability that the B -types might block A increases. Because the above effect of lowering q applies to both groups, it is not clear which group benefits from this change.

To demonstrate the ambiguous effect of lowering q consider the following example: let $n = 1000$ (in light of Proposition 5 we intentionally pick a large n), $p = 0.4$ and consider the distribution function $F(u) = 1 - \frac{1}{\sqrt{\ln(u+e)}}$. For $q = 300$ there exists a minority equilibrium $u_A \simeq 1.35$ and $u_B \simeq 80$. However, for $q = 10$ there exists no minority equilibrium.

The above example seems to suggest that for some distribution functions a minority equilibrium may not exist when the supermajority requirement is *at unanimity*. Indeed, this is true.

Proposition 4. *Suppose that the distribution of u , $F(u)$, satisfies the condition*

$$\frac{f(x)}{1 - F(x)} \leq \frac{1}{(1 + x) \ln(1 + x)} \tag{7}$$

for all $x > 0$. Then in the case where $m = n$ —i.e., unanimity—a minority equilibrium cannot exist for any n .

Note that cdf from the above example, $F(u) = 1 - \frac{1}{\sqrt{\ln(u+e)}}$, satisfies the sufficient condition (7). Moreover, while conceivably not necessary, *some* condition is needed to rule out minority equilibria in the unanimity case: there do exist cdf’s for which minority equilibria exist for all large n .⁹

⁹ One example of such a cdf is the exponential distribution $F(u) = 1 - e^{-u}$.

Finally, compare and contrast our findings with the asymmetric equilibria in the Battle of the Sexes (BoS). Recall that analogues of those equilibria exist in this model as well, *but they have already been eliminated by the refinement introduced in Section 4.2.2*. One might suspect that the equilibria of our model converge (as n grows large) to the equilibria of the BoS game. In this sense, the equilibria could be perceived as purification of the BoS equilibria. However, Proposition 4 establishes that this is not the case. Indeed, in some cases, minority equilibria do not exist for any n . Hence, uncertainty plays a crucial role in our model. This conclusion will be further strengthened when we study limit outcomes in Section 6.

5.3. Minorities win in minority equilibrium

In this section we address the distinction between an equilibrium in which one group *behaves* more aggressively, and one in which that group *wins* more often. For instance, in the majority equilibrium the majority fights harder *and* wins more often than the minority does. (It cannot be otherwise, the majority are ahead both in numbers and aggression.) But there is no reason to believe that the same is true of the minority equilibrium. The minority may be more aggressive, but the numbers are not on their side.

However, a remarkable property of this model is that a minority equilibrium *must involve the minority winning with greater probability than the majority*. Provided that a minority equilibrium exists, aggression must compensate for numbers.

Proposition 5. *In a minority equilibrium, the minority outcome is implemented with greater probability than the majority outcome.*

This framework therefore indicates quite clearly how group behavior in a given situation may be swayed both by majority and minority concerns. When the latter occurs, it turns out that we have some kind of “tyranny of the minority”: they are so vocal that they actually swing outcomes (in expectation) to their side.

The proof of this proposition is so simple that we provide it in the main text, in the hope that it will serve as its own intuition.

Proof. Recall (5) and (6) and note that $u_A < u_B$ in a minority equilibrium. It follows right away that $\sum_{k=0}^q \binom{m-1}{k} \pi^k (1-\pi)^{m-1-k} > \sum_{k=0}^q \binom{m-1}{k} \sigma^k (1-\sigma)^{m-1-k}$, so that $\pi < \sigma$. Expanding this inequality, we conclude that $\lambda_B(1-\lambda_B) < \lambda_A(1-\lambda_A)$. Because $\lambda_A < \frac{1}{2}$, this can only happen in two ways: either $\lambda_B > 1-\lambda_A$, or $\lambda_B < \lambda_A$. The former case is impossible, because λ_A and λ_B describe mutually exclusive events, so the latter case must obtain. But this implies the truth of the proposition. \square

6. Limit equilibria

In Section 5.1 we established the existence of a minority equilibrium. Existence was guaranteed for large n and for all supermajority rules except for unanimity. As we have already remarked, there must be at least two such equilibria, while in addition we know that there is at least one majority equilibrium. This raises the question of what the set of equilibria look like as the group size grows without bound.

The purpose of this section is to prove that despite the possibly large multiplicity of equilibria for finite group size, there are exactly three limit outcomes. Two of these outcomes are “limit

minority equilibria”. Of the two, one exhibits a zero cutoff for the minority, and the other exhibits a positive minority cutoff which is nevertheless lower than the majority cutoff. The third outcome is a “limit majority equilibrium” in which the cutoff used by the majority is zero.

Moreover, the two corner equilibria (in which one side always fights for its favorite) possess a special structure: *the other side does not necessarily yield fully*. That is, the rival side may use an interior cutoff even in the limit, and we will characterize this cutoff exactly.

We will also study disagreement probabilities along any sequence of equilibria.

6.1. A characterization of limit outcomes

We now study the various limit points of equilibrium cutoff sequences. We will denote a generic limit point by (u_A^*, u_B^*) .

Proposition 6. Assume that $v > 0$.

- (1) Suppose that $(u_A^*, u_B^*) \gg 0$. Then both limits must be finite, and solve

$$p[1 - F(u_A^*)] = (1 - p)[1 - F(u_B^*)] = v. \tag{8}$$

- (2) Suppose that $u_A^* = 0$. Then $u_B^* < \infty$ if and only if $p < (1 - v)/v$, and in that case u_B^* is given by the condition

$$F(u_B^*) = \frac{p(1 - 2v)}{(1 - p)v}. \tag{9}$$

- (3) Likewise, suppose that $u_B^* = 0$. Then $u_A^* < \infty$ if and only if $1 - p < (1 - v)/v$, and in that case u_A^* is given by the condition

$$F(u_A^*) = \frac{(1 - p)(1 - 2v)}{pv}. \tag{10}$$

- (4) Moreover, if $p > v$, each of the three configurations described above are limits for some sequence of equilibria.

Proposition 6 is best understood by looking at Fig. 3, which is drawn for the “semi-corner case” in which $v < p < 1 - p < v/(1 - v)$. This figure depicts the loci $\lambda_B/(1 - \lambda_A) = v/(1 - v)$ and $\lambda_A/(1 - \lambda_B) = v/(1 - v)$, suitably truncated to respect the constraints that $\lambda_A \leq p$ and $\lambda_B \leq 1 - p$. We claim that limit equilibrium cutoffs must simultaneously lie on *both* these truncated loci. To see this, suppose that some cutoff sequence $\{\lambda_A^n, \lambda_B^n\}$ lies below the locus $\lambda_B/(1 - \lambda_A) = v/(1 - v)$ (along some subsequence, but retain the original index n). Then the equilibrium condition (5), coupled with the strong law of large numbers, assures us that $u_A^n \rightarrow 0$, or that $\lambda_A^n \rightarrow p$, which pulls the system back on to the locus. If, on the other hand, the cutoff sequence $\{\lambda_A^n, \lambda_B^n\}$ lies above the locus $\lambda_B/(1 - \lambda_A) = v/(1 - v)$, we have a contradiction as follows. First, by using (5) again, we may conclude that $\lambda_A^n \rightarrow 0$. Next, recall that $\lambda_B^n \leq 1 - p < v/(1 - v)$ (by assumption), but this and the previous sentence contradict the presumption that $\lambda_B^n/(1 - \lambda_A^n) > v/(1 - v)$ for all n .

Of course, the same sort of argument applies to both loci, so we may conclude that equilibrium cutoffs must converge to one of three intersections displayed in Fig. 3.¹⁰

¹⁰ It is also possible to construct versions of this diagram for the other cases, such as $1 - p > v/(1 - v)$ but $p < v/(1 - v)$.

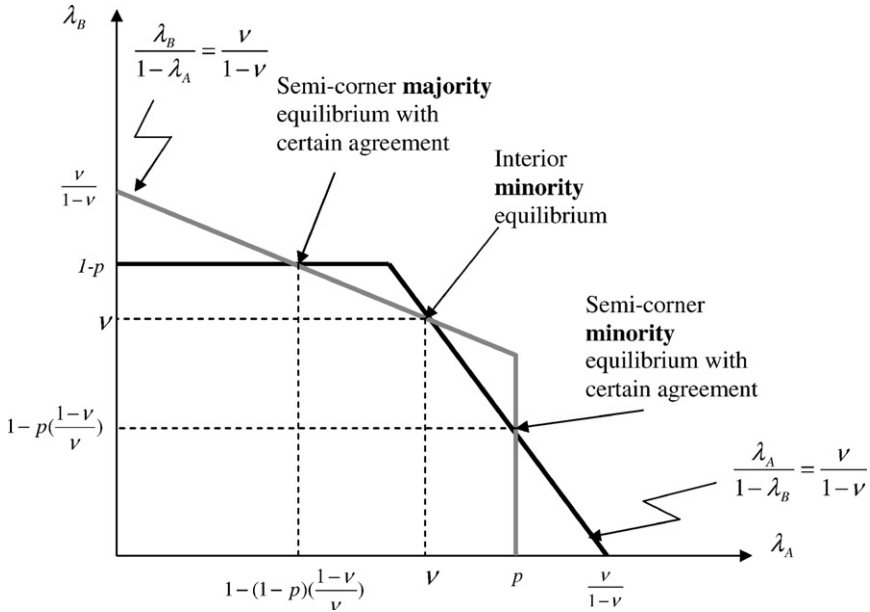


Fig. 3. Limit equilibrium cutoffs.

The last part of the proposition asserts that when minority equilibria exist for large n , each of the three cases indeed represent “bonafide” limit points, in that each case is an attractor for some sequence of equilibria. For the majority corner, this is obvious, as majority equilibria always exist and no sequence of majority equilibria can ever converge to a minority outcome. That the other two limits are also non-vacuous follow from the proof of existence of minority equilibria (the reader is invited to study the formal arguments in Section 9).

6.2. Disagreement

One important implication of Proposition 6 is that even when there is little uncertainty regarding the size of each faction, both sides may still put up a fight. In particular, when $1 - p < \frac{1-v}{v}$ all limit equilibria consist of “fighting” on both sides. This raises the question of whether disagreement is bound to occur in large populations.

Proposition 7. Assume $v > 0$.

- (1) Suppose that $v < p < \frac{1-v}{v}$ and let u_B^* be the limit cutoff value that solves (9). Then in the limit semi-corner equilibrium $(0, u_B^*)$ both sides agree with certainty.
- (2) Assume $1 - p < \frac{1-v}{v}$ and let u_A^* be the limit cutoff value that solves (10). Then in the limit semi-corner equilibrium $(u_A^*, 0)$ both sides agree with certainty.
- (3) Consider any sequence of equilibria $(u_A^n, u_B^n) \rightarrow (u_A^*, u_B^*)$ where u_A^* and u_B^* solve (8). Then the probability of disagreement along that sequence is bounded away from one.

The proofs of (1) and (2) follow immediately by looking at Fig. 3. At the semi-corner minority equilibrium the proportion of A votes is simply p , which is strictly greater than v . The proportion of B votes is $1 - p[(1 - v)/v]$, which is strictly smaller than v . It follows that in the limit A is

the unique eligible alternative, and hence that A will be implemented with certainty. Analogous arguments show that in the semi-corner majority equilibrium, B is the unique eligible alternative.

The proof of (3) is more involved. Recall that in this case the proportion of A and B votes converges to the superminority requirement v . One may be tempted to conclude that the probability of disagreement in this case must converge to $\frac{1}{4}$. A closer examination reveals that this may not be the case. Indeed, what is important in determining the probability of disagreement is not the mere convergence of λ_A and λ_B to v , but their *rate* of convergence. So far, the equilibrium conditions do not allow us to pin down the probability of disagreement in this case. Still, we establish that this probability is bounded away from one.

The intuition for this result is the following. Suppose that the probability of disagreement is high. Then the probability that each group is blocking the supermajority of its rival is also high. In particular, this means that group cutoffs are not wandering off to infinity. On the other hand, we can see that if group A , for example, is blocking group B , then the latter will be discouraged from making a B announcement. Doing so will most likely lead to disagreement, while casting a neutral vote ensures an agreement on A . This argument makes for high cutoffs, a contradiction to the bounded group cutoffs that were asserted earlier in this paragraph.

In part, the formalization of the above intuition is easy, but the simultaneous movements in population size and cutoffs necessitate a subtle argument. In particular, the last implication—that cutoffs become large with population size—rests on arguments regarding *rates* of change as a function of population. The reader is referred to the formal proof for details.

What allows individuals to agree, even when there are great many of them, is the option to remain neutral. This can be seen if we analyze a restricted version of our model in which individuals have only two options: A or B . We carry out this analysis in Section 7.3. There, we show that Proposition 7 ceases to hold.

Finally, note that the case of unanimity is *not* covered here. This question remains open.

7. Extensions

7.1. Biased choice when both alternatives are eligible

Our model emphasizes majorities and minorities, but it can be used to study other issues. Consider the following example involving “bias”. Suppose that an interested arbitrator or chair gets to implement the outcome in case both options are eligible.¹¹ To focus directly on the issue at hand, assume that the model is symmetric in every respect (inclusive of $p = \frac{1}{2}$, though this is not logically needed for what follows) except for the bias, which we denote by $\alpha > \frac{1}{2}$ in favor of alternative B .

It stands to reason that the presence of such a bias will spur A types on to greater aggression in pushing their alternative, while it might make the B types more complacent. This much is fairly obvious¹²: the question is whether such behavioral changes might nullify or even outweigh the bias.

The case of a strong bias, in which $\alpha \simeq 1$, is easiest to consider, because it has an unambiguous prediction:

¹¹ We owe this subsection to the comments of a referee.

¹² Formally, with multiple equilibria we would have to analyze changes in the equilibrium *correspondence*, but the reasonable conjecture in the main text can be easily made precise.

Observation 5. *Along any sequence of equilibria (as $\alpha \rightarrow 1$), it must be the case that $\lambda_B \rightarrow 0$, and $\lambda_A \rightarrow p = \frac{1}{2}$.*

While a formal proof is postponed to Section 9, the intuition is simple. The B types know that as long as B is eligible, it is very likely to win. But pushing *just* B serves no additional purpose except to create a possible gridlock, which is damaging. Hence type B 's equilibrium response must converge to “full neutrality” as $\alpha \rightarrow 1$. For the A types, then, full aggression becomes an equilibrium response: they know that the eligibility of both alternatives is the same as an almost-sure defeat, and there is little likelihood of disagreement (given the timidity of the B s).

The implication of these results is that the probability of A winning must converge to precisely the probability that the A types number more than q in the population. For A wins only when the A types block B , and triumph as the only eligible alternative. Otherwise it loses. If $q < n/2$ (so that we are dealing with supermajority rules), this probability must exceed $\frac{1}{2}$. In contrast, when there is no bias, the model is completely symmetric and the probability that A wins must be no more than half, *ex-ante*.¹³

We have therefore shown that arbitration biases against an alternative may increase the winning probability of that alternative, and indeed will increase it when the arbitration bias is infinitely high.

7.2. More on tie-breaking

The discussion in the previous section may be viewed more generally as an instance of various tie-breaking scenarios when both alternatives are eligible. For example, one might simply have a majority vote or some other “runoff” in this case. The parameter α in Section 7.1 may be viewed as the reduced-form probability of win for type B in the runoff following eligibility of both alternatives. This makes little difference to the formalities of the model. One would simply redefine the variable u , depending on the value of α (the proof of Observation 5 in Section 9 does just this).

An interesting special case arises when α is given by a simple majority runoff. In this case, by Observation 2, α must equal $1 - p$, a bias towards the majority. This is an additional source of minority aggression, as suggested by the analysis of the previous section.

Other tie-breaking procedures are harder to handle within our framework. For instance, suppose that the outcome with the more votes is chosen in the event that both outcomes are eligible. (The *existing* votes are recounted, so this is different from a runoff.) This leads to a more complicated setup; we indicate some of the steps.

Begin by deriving the necessary and sufficient condition for an individual of some type, say A , to weakly prefer an announcement of his favorite outcome— A in this case—to neutrality. To simplify the exposition we introduce the following notation. Define τ to be the joint probability that not counting our individual's vote, both A and B are eligible and both have the same number of declarations. Similarly, we define τ' to be the joint probability that not counting the A type's vote, both A and B are eligible, both have strictly less than q declarations, but B has exactly one declaration more than A . We also use the notation P^+ defined in Section 4.1.

¹³ The qualification “no more than half” stems from the possibility of disagreement. However, remember that there may be multiple equilibria, so our statement in the text may be viewed as the outcome of symmetric randomization over all equilibria.

Given the above tie-breaking rule, an *A* type weakly prefers to declare *A* than to declare neutrality if, and only if

$$\tau v + \tau' \left(\frac{v + v'}{2} \right) \geq P^+ v' + \tau' v' + \tau \left(\frac{v + v'}{2} \right).$$

Simplifying this inequality we obtain the following cutoff rule: declare *A* if, and only if

$$(\tau + \tau') u \geq P^+.$$

It follows that as in our original model, individuals base their decisions on how strongly they favor their preferred outcome to the alternative one. A similar inequality is obtained for the *B* types.

The complexity involved in analyzing our model under this alternative tie-breaking rule follows from the above inequality. Recall that in our original formulation the cutoff rule was expressed as the lower tail of a binomial distribution. Unfortunately, the new formulation does not accommodate such an expression.

Despite the added complexity, we are able to replicate some of our original results. First, it can be shown that all symmetric equilibria are interior (this is stated and proved as Observation 8 in Section 9). In contrast to the corresponding result in the paper (Observation 1), this result does not rely on any refinement. Second, a majority equilibrium always exists. This follows from arguments similar to those made in Proposition 1.

Establishing the existence of a minority equilibrium proved to be a formidable task. However, it is easy enough to generate numerical examples that exhibit the same features as those described in Proposition 2.¹⁴

7.3. No neutrality

In our opinion, when faced with impending disagreement, the option of a neutral stance is very natural. This is why we adopted this specification in our basic model. (As discussed already, neutrality is not to be literally interpreted as a formal announcement.) Nevertheless, it would be useful to see if the insights of the exercise are broadly preserved if announcements are restricted to be either *A* or *B*.

We can quickly sketch such a model. An individual is now pivotal under two circumstances. In the first event, the number of people announcing her favorite outcome is exactly *q*, which we assume to be less than $(n - 1)/2$.¹⁵ By announcing her favorite, then, disagreement is the outcome, while an announcement of the other alternative would lead to that alternative being implemented. The loss, then, from voting one’s favorite in this event is precisely *v'* (recall that the disagreement payoff is normalized to zero). In the second event, the number of people announcing the alternative is exactly *q*. By announcing her favorite, she guarantees its implementation, while the other announcement would lead to disagreement. So the gain from voting one’s favorite in this event is *v*. Consequently, an individual will announce her favorite if

$$\Pr(\text{exactly } q \text{ others vote for alternative})v \geq \Pr(\text{exactly } q \text{ others vote for favorite})v'.$$

¹⁴ For example, a minority equilibrium exists for $F(u) = 1 - e^{-3u}$, $p = 0.4$, $n = 19$ and $q = 3$.

¹⁵ The case $q = (n - 1)/2$ is exactly the same as in Observation 2 for the main model. No matter what the valuations are, each individual will announce her favorite outcome.

Define $w \equiv v/v'$. Then equilibrium cutoffs w_A and w_B are given by the conditions

$$w_A \Pr(|B| = q) \geq \Pr(|A| = q) \tag{11}$$

and

$$w_B \Pr(|A| = q) \geq \Pr(|B| = q), \tag{12}$$

where $|A|$ and $|B|$ stand for the number of A - and B -announcements out of $n - 1$ individuals, and where equality must hold in each of the conditions provided the corresponding cutoff strictly exceeds 1, which is the lower bound for these variables.

In this variation of the model, it is obvious that at least one group must be “fully aggressive” (i.e., its cutoff must equal one).¹⁶ Moreover, as long as we are in the case $q < (n - 1)/2$, both groups cannot *simultaneously* be “fully aggressive”: one of the cutoffs must strictly exceed unity.

So, in contrast to our model, in which all (robust) equilibria are fully interior, the equilibria here are at “corners” (full aggression on one side, full acquiescence on the other) or “semi-corners” (full aggression on one side, interior cutoffs on the other). The semi-corner equilibria are always robust in the sense of Section 4.2.2, and we focus on these in what follows.¹⁷

In particular, to examine possible minority equilibria, set $w_A = 1$. Then use the equality version of (12) to assert that

$$w_B = \left(\frac{p + (1 - p)H(w_B)}{(1 - p)[1 - H(w_B)]} \right)^{n-1-2q} \tag{13}$$

in any such equilibrium, where H is the (assumed atomless) cdf of w , distributed on its full support $[1, \infty)$.

It is easy to use (13) to deduce

Observation 6. (1) *A semi-corner minority equilibrium exists if (n, q) are sufficiently large.*

(2) *In any minority equilibrium, the minority outcome is implemented with greater probability than the majority outcome.*

So the broad contours of our model can be replicated in this special case. This is reassuring, because it reassures us of the robustness of the results. At the same time this variation allows us to highlight the main implication of allowing voters to remain neutral: absent neutrality voters may be locked into situations in which they are almost certain to disagree. This is formalized in the next result.

Observation 7. *Assume $0 < v < p < \frac{1}{2}$. Consider any sequence $\{n, q\}$ such that $n \rightarrow \infty$ and q is one of the two integers closest to vn . Then there exists a sequence of semi-corner minority equilibria for which the probability of disagreement converges to one.*

The above result demonstrates the importance of being neutral: neutrality allows the players to avoid disagreement. Recall that Proposition 7 establishes that with neutrality, the probability of disagreement at every interior equilibrium is bounded away from one. Once the option of neutrality is taken away, the probability that players reach a disagreement (at any interior equilibrium) must go to one along some sequence of minority equilibria.

¹⁶ Simply examine (11) and (12) and note that both right-hand sides cannot strictly exceed one.

¹⁷ In contrast to our setup, the “full corner” equilibria may or may not be robust. We omit the details of this discussion.

7.4. Known group size

Our model as developed has the potential drawback that the instance of a known group size is not a special case. More generally, individuals may have substantial information regarding the ordinal stance of others (though still remaining unsure of their cardinal preferences).¹⁸

One way to accommodate this concern is to amend the model to posit a probability distribution $\theta(n_A)$ over the number n_A of A -types in the population. (The current specification of cardinal intensities may be retained.) This has the virtue of nesting our current model as well as known group size as special cases.¹⁹ In addition, the basic structure of our model is easily recreated in this more general setting. For instance, if θ exhibits full support, a similar robustness argument applies to eliminate the “coordination-failure” corner equilibria, and downward-sloping “reaction functions”, as in Fig. 1, may be constructed just as before. The concept of a stochastic minority can also be easily extended. However, there are interesting conceptual issues involved in *changing* group size: in particular, we will need to specify carefully how θ alters in the process.

While a full analysis of this model is “beyond the scope of the current paper”, we provide some intuition by studying the extreme case in which group size is known; i.e., $\theta(n_A) = 1$ precisely at some integer $n_A < n/2$. We retain all our other assumptions.

Of course, θ no longer has full support, so the arguments in Section 4.2.2 do not apply to this case. To see why, consider the case when all B types are voting for B , whereas only extreme A -types are voting for A . When an A -type knows exactly how many B -types there are, he realizes that he can only create a disagreement by voting for A . Therefore, when group sizes are known, the two corner equilibria are robust (in the sense of Section 4.2.2). This suggests that the corner equilibria are unnatural in the following sense: when faced with some uncertainty about group sizes, some individuals may still put up a fight.

A further observation relates to the importance of group size in the emergence of minority equilibria. Potentially, the existence of minority equilibria in our original model may be due to two types of uncertainties that are relaxed in large groups. First, as the number of individuals in the group increases, voters have a more accurate estimate of the proportion of their types in the group. Second, as the population increases, each individual has a better picture of the distribution of intensities among his compatriots.

What if group sizes are known? Then it can easily be shown that the equilibrium cutoff for one type depend only on the equilibrium cutoff of the other type. More precisely, an equilibrium (u_A, u_B) satisfies the following equations:

$$(1 + u_A) \sum_{k=0}^q \binom{n_B}{k} (F(u_B))^{n_B-k} (1 - F(u_B))^k = 1,$$

$$(1 + u_B) \sum_{k=0}^q \binom{n_A}{k} (F(u_A))^{n_A-k} (1 - F(u_A))^k = 1,$$

where $n_A < n_B$ are the number of individuals of type A and B , respectively.

It is straightforward to construct examples in which there does not exist a minority equilibrium for small n_A and n_B . For instance, take $F(u) = 1 - \frac{1}{\sqrt{\ln(u+\epsilon)}}$, $n_A = 2$, $n_B = 3$ and $q = 1$. For these values there exists a unique interior majority equilibrium, $u_A \approx 250$ and $u_B \approx 0.22$. However, using arguments similar to those employed in Propositions 2 and 4, one can show that

¹⁸ In our current model, such “substantial information” is only possible if p is close to either 0 or 1.

¹⁹ In the current model, $\theta(n_A) = \binom{n}{n_A} p^{n_A} (1 - p)^{n-n_A}$ for some $p \in (0, \frac{1}{2})$.

for large n a minority equilibrium exists and the probability of disagreement is bounded away from one. By simple stochastic dominance arguments, it can be shown that in any minority equilibrium the minority wins more often.

We conclude that certainty regarding the numbers of A and B types is not sufficient to generate a minority equilibrium; even when the numbers of A and B types are known, we still need n to be sufficiently large for the minority to prevail.

7.5. Types who prefer disagreement to the rival alternative

Suppose there exist types who rank disagreement above their second best alternative. Clearly, voting for the preferred alternative is weakly dominant for these types. Hence, in any interior equilibrium these individuals would vote their type. In this sense, incorporating these voters into our model is equivalent to adding aggregate noise. We believe that if the proportion of such types is sufficiently low, all of our results continue to hold.

8. Summary

We study a model of group decision-making in which one of two alternatives must be chosen. While group members differ in their valuations of the alternatives, everybody prefers some alternative to disagreement.

We uncover a variant on the “tyranny of the majority”: there is always an equilibrium in which the majority is more aggressive in pushing its alternative, thus enforcing their will via both numbers and voice. However, under very general conditions an aggressive minority equilibrium inevitably makes an appearance, provided that the group is large enough. This equilibrium displays a “tyranny of the minority”: it is always true that the increased aggression of the minority more than compensates for smaller number, leading to the minority outcome being implemented with larger probability than the majority alternative.

These equilibria are not to be confused with “corner” outcomes in which a simple failure of coordination allows any one group to be fully aggressive and another to be completely timid, without regard to group size. Indeed, one innovation of this paper is to show how such equilibria are entirely non-robust when confronted with varying intensities of valuations, and some amount of uncertainty regarding such valuations. In fact, as we emphasize in the paper, minority equilibria do not always exist: they do not exist, in general, for low population sizes and in the unanimity case they may not exist for *any* population size.

We also fully characterize limit outcomes as population size goes to infinity. We show that there are exactly three limit outcomes to which all equilibria must converge. Two of these outcomes are “limit minority equilibria”. Of the two, one exhibits a zero cutoff for the minority, and the other exhibits a positive minority cutoff which is nevertheless lower than the majority cutoff. The third outcome is a “limit majority equilibrium” in which the cutoff used by the majority is zero. The two corner equilibria which display full aggression on one side do not, in general, force complete timidity on the rival side. We provide a complete characterization by providing necessary and sufficient conditions for the interiority of such cutoffs and describing exactly their values.

Finally, we address the question of disagreement as group size grows large. We show that the probability of disagreement must converge to zero along all equilibrium sequences that converge to the semi-corners identified above. For those equilibria that converge to the remaining interior minority outcome, we show that the probability of disagreement is bounded away from one as the population size goes to infinity. The option to remain neutral is crucial in obtaining this result.

Observation 7 in Section 7 considers an extension in which the neutrality option is removed, and proves that there is always a sequence of equilibria (in group size) along which the probability of disagreement must converge to one.

While we focus on the positive aspects of supermajority rules, our analysis suggests an approach from the viewpoint of mechanism design. Under supermajority rules, the fear of possible disagreement induces agents to base their actions on their *cardinal* preferences, rather than just on their ordinal ranking as in simple majority. Individuals who care a lot about the final outcome will indeed risk disagreement. Thus supermajority rules in the shadow of disagreement plays a possible role in eliciting intensities. However, there are caveats. First, disagreement is costly. It remains to be seen whether groups would obtain a net benefit by committing to the use of this costly option. Second, as our analysis shows, what determines agent behavior are *relative*, not absolute preference intensities over the different outcomes (see also [14]). This is an important (and complicated) enough question that deserves to be addressed in a separate paper.

9. Proofs

Proof of Observation 3. For concreteness, set $i = A$ and $j = B$. Fix any $u_B \in [0, \infty)$. Recall that

$$\pi = \frac{\lambda_B}{1 - \lambda_A} = \frac{(1 - p)[1 - F(u_B)]}{1 - p[1 - F(u_A)]},$$

so that π is continuous in u_A , with $\pi \rightarrow 1 - F(u_B)$ as $u_A \rightarrow 0$, and $\pi \rightarrow (1 - p)[1 - F(u_B)]$ as $u_A \rightarrow \infty$. Consequently, recalling (5) and noting that $q < (n - 1)/2$, we see that $\alpha(u_A, u_B)$ converges to a number strictly less than one as $u_A \rightarrow 0$, while it becomes unboundedly large as $u_A \rightarrow \infty$. By continuity, then, there exists some u_A such that $\alpha(u_A, u_B) = 1$, establishing the existence of a cutoff.

To show uniqueness, it suffices to verify that α is strictly increasing in u_A . Because the expression $\sum_{k=0}^q \binom{m-1}{k} \pi^k (1 - \pi)^{m-1-k}$ must be decreasing in π , it will suffice to show that π itself is declining in u_A , which is a matter of simple inspection.

To show that the response u_A strictly decreases in u_B , it will therefore be enough to establish that α is also increasing in u_B . Just as in the previous paragraph, we do this by showing that π is decreasing in u_B , which again is a matter of elementary inspection.

Finally, we observe that $u_A \downarrow 0$ as $u_B \uparrow \infty$. Note that along such a sequence, $\pi \rightarrow 0$ regardless of the behavior of u_A . Consequently, $\sum_{k=0}^q \binom{m-1}{k} \pi^k (1 - \pi)^{m-1-k}$ converges to 1 as $u_B \uparrow \infty$. To maintain equality (5), therefore, it must be the case that $u_A \downarrow 0$.

Of course, all these arguments hold if we switch A and B . \square

Proof of Observation 4. Let \bar{u} be defined as in the statement of this observation. Define $\bar{\lambda}_A \equiv p[1 - F(\bar{u})]$ and $\bar{\lambda}_B \equiv (1 - p)[1 - F(\bar{u})]$. Then

$$(1 + \bar{u}) \sum_{k=0}^q \binom{m-1}{k} \bar{\pi}^k (1 - \bar{\pi})^{m-1-k} = 1, \tag{14}$$

where $\bar{\pi} \equiv \bar{\lambda}_B / (1 - \bar{\lambda}_A)$. Now recall that σ in (6) is defined by $\sigma = \frac{\lambda_A}{1 - \lambda_B}$, so that if we consider the corresponding value $\bar{\sigma}$ defined by setting $u_A = u_B = \bar{u}$, we see that

$$\bar{\sigma} \leq \bar{\pi} \text{ if and only if } \bar{\lambda}_A(1 - \bar{\lambda}_A) \leq \bar{\lambda}_B(1 - \bar{\lambda}_B).$$

But $\lambda_A \leq \frac{1}{2}$ (because $p \leq \frac{1}{2}$), so that the second inequality above holds if and only if $\bar{\lambda}_A \leq \bar{\lambda}_B$, and this last condition follows simply from the fact that $p \leq \frac{1}{2}$.

So we have established that $\bar{\sigma} \leq \bar{\pi}$. It follows that

$$\sum_{k=0}^q \binom{m-1}{k} \bar{\pi}^k (1 - \bar{\pi})^{m-1-k} \leq \sum_{k=0}^q \binom{m-1}{k} \bar{\sigma}^k (1 - \bar{\sigma})^{m-1-k}$$

and using this information in (14), we must conclude that

$$\beta(\bar{u}, \bar{u}) = (1 + \bar{u}) \sum_{k=0}^q \binom{m-1}{k} \bar{\sigma}^k (1 - \bar{\sigma})^{m-1-k} \geq 1. \tag{15}$$

Recalling that β is increasing in its first argument (see proof of Observation 3), it follows from (15) that type B 's equilibrium response to \bar{u} is no bigger than \bar{u} .

Finally, observe that all these arguments apply with strict inequality when $p < \frac{1}{2}$. \square

Proof of Proposition 1. For each $u_B \geq 0$, define $\phi(u_B)$ by composing equilibrium responses: $\phi(u_B)$ is B 's equilibrium response to A 's equilibrium response to u_B . By Observation 3, we see that A 's equilibrium response is a positive, finite value when $u_B = 0$, and therefore so is B 's response to this response. Consequently, $\phi(0) > 0$. On the other hand, A 's equilibrium response is precisely \bar{u} when $u_B = \bar{u}$, and by Observation 4 we must conclude that $\phi(\bar{u}) < \bar{u}$. Because ϕ is continuous (Observation 3 again), there is $u_B^* \in (0, \bar{u})$ such that $\phi(u_B^*) = u_B^*$. Let u_A^* be type A 's equilibrium response to u_B^* . Then it is obvious that (u_A^*, u_B^*) is an equilibrium. Because $u_B^* < \bar{u}$, we see from Observation 3 that $u_A^* > \bar{u}$. We have therefore found a majority equilibrium. \square

Proposition 2 and some subsequent arguments rely on the following lemma.

Lemma 1. Consider any sequence $\{n, q\}$ such that $n \rightarrow \infty$ and q is one of the two integers closest to vn . For any \bar{u}_A satisfying

$$p[1 - F(\bar{u}_A)] > v, \tag{16}$$

there exists a finite N such that for all $n \geq N$, $\hat{u}_B^n > u_B^n > \bar{u}_A$ where u_B^n solves (5) with $u_A = \bar{u}_A$, and \hat{u}_B^n solves (6) with $u_A = \bar{u}_A$.

Proof. Consider any sequence $\{n, q\}$ as described in the statement of the lemma. Because $p > v$, there exists a range of positive cutoff values satisfying inequality (16). Consider any such value \bar{u}_A and denote $\bar{\lambda}_A \equiv p[1 - F(\bar{u}_A)]$. There exists a finite n^* such that for all $n \geq n^*$,

$$\bar{\lambda}_A > \frac{q}{n-1} \simeq v$$

Note that there is also an associated sequence $\{m\}$ defined by $m_n \equiv n - q$.²⁰

We break the proof up into several steps.

Step 1: We claim that there exists an integer M such that for each $m \geq M$ there is $u_B^m < \infty$ that solves the following equation:

$$\sum_{k=0}^q \binom{m-1}{k} (\pi_m)^k (1 - \pi_m)^{m-1-k} = \frac{1}{1 + \bar{u}_A}, \tag{17}$$

²⁰ While correct notation would demand that we denote this sequence by m_n , we shall use the index m for ease in writing.

where

$$\pi_m \equiv \frac{\lambda_B^m}{1 - \bar{\lambda}_A}$$

and

$$\lambda_B^m \equiv (1 - p) [1 - F(u_B^m)].$$

We prove this claim. Note that for all $n \geq n^*$, $1 - p \geq p > q/(n - 1)$, so that

$$\bar{\pi} \equiv \frac{(1 - p)(n - 1)}{m - 1} > \frac{q}{m - 1} \simeq \frac{v}{1 - v}$$

for all $n \geq n^*$. Consequently, by the strong law of large numbers (SLLN),

$$\sum_{k=0}^q \binom{m - 1}{k} \bar{\pi}^k (1 - \bar{\pi})^{m-1-k} \rightarrow 0$$

as m and q grow to infinity. It follows that there exists M such that for all $m \geq M$ (and associated q),

$$\sum_{k=0}^q \binom{m - 1}{k} \bar{\pi}^k (1 - \bar{\pi})^{m-1-k} < \frac{1}{1 + \bar{u}_A}. \tag{18}$$

For such m , provisionally consider $u_B^m = 0$. Then

$$\frac{\lambda_B^m}{1 - \bar{\lambda}_A} = \frac{1 - p}{1 - p [1 - F(\bar{u}_A)]}$$

and using this in (16), we conclude that

$$\pi_m = \frac{\lambda_B^m}{1 - \bar{\lambda}_A} = \frac{1 - p}{1 - p [1 - F(\bar{u}_A)]} > \frac{(1 - p)(n - 1)}{m - 1} = \bar{\pi}.$$

Combining this information with (18), we see that if $u_B^m = 0$, then

$$\sum_{k=0}^q \binom{m - 1}{k} \pi_m^k (1 - \pi_m)^{m-1-k} < \frac{1}{1 + \bar{u}_A}. \tag{19}$$

Next, observe that if u_B^m is chosen very large, then λ_B^m and consequently π_m are both close to zero, so that $\sum_{k=0}^q \binom{m-1}{k} \pi_m^k (1 - \pi_m)^{m-1-k}$ is close to unity. It follows that for such u_B^m ,

$$\sum_{k=0}^q \binom{m - 1}{k} \pi_m^k (1 - \pi_m)^{m-1-k} > \frac{1}{1 + \bar{u}_A}. \tag{20}$$

Combining (19) and (20) and noting that the LHS of (17) is continuous in u_B^m , it follows that for all $m \geq M$ there exists $0 < u_B^m < \infty$ such that the claim is true.

Step 2: One implication of (17) in Step 1 is the following assertion: as $(m, q) \rightarrow \infty$,

$$\pi_m \rightarrow v/(1 - v) \in (0, 1), \text{ and in particular, } u_B^m \text{ is bounded.} \tag{21}$$

To see why, note that $\frac{1}{1 + \bar{u}_A} \in (0, 1)$. Using (17) and SLLN, it must be that $\pi_m \rightarrow v/(1 - v) \in (0, 1)$ as $(m, q) \rightarrow \infty$. Recalling the definition of π_m it follows right away that u_B^m must be bounded.

Step 3: Next, we claim there exists an integer M^* such that

$$\text{For all } m \geq M^*, u_B^m > \bar{u}_A. \tag{22}$$

To establish this claim, note first, using (16), that

$$p [1 - F(\bar{u}_A)] > \frac{q}{n-1} = \frac{\frac{q}{m-1}}{1 + \frac{q}{m-1}} \geq \frac{\frac{q}{m-1}}{\frac{1-p}{p} + \frac{q}{m-1}},$$

where the last inequality follows from the assumption that $p \in (0, \frac{1}{2}]$, so that $\frac{1-p}{p} \geq 1$. A simple rearrangement of this inequality shows that

$$\frac{(1-p)[1 - F(\bar{u}_A)]}{1 - p[1 - F(\bar{u}_A)]} > \frac{q}{m-1} \simeq \frac{v}{1-v}. \tag{23}$$

Now suppose, contrary to the claim, that $u_B^m \leq \bar{u}_A$ along some subsequence of m . Then on that subsequence,

$$\pi_m = \frac{\lambda_B^m}{1 - \bar{\lambda}_A} = \frac{(1-p)[1 - F(u_B^m)]}{1 - p[1 - F(\bar{u}_A)]} \geq \frac{(1-p)[1 - F(\bar{u}_A)]}{1 - p[1 - F(\bar{u}_A)]}. \tag{24}$$

Combining (23) and (24), we may conclude that along the subsequence of m for which $u_B^m \leq \bar{u}_A$,

$$\inf_m \pi_m > \frac{v}{1-v},$$

which contradicts (21) of Step 2.

To prepare for the next step, let \hat{u}_B^m denote the equilibrium response of the B -types to $u_A = \bar{u}_A$. That is,

$$\frac{1}{1 + \hat{u}_B^m} = \sum_{k=0}^q \binom{m-1}{k} \sigma_m^k (1 - \sigma_m)^{m-1-k}, \tag{25}$$

where

$$\sigma_m \equiv \frac{\bar{\lambda}_A}{1 - \hat{\lambda}_B^m}$$

and

$$\hat{\lambda}_B^m \equiv (1-p)[1 - F(\hat{u}_B^m)].$$

Step 4: There is an integer M^{**} such that for all $m \geq M^{**}$, $\hat{u}_B^m > u_B^m$.

To prove this claim, suppose on the contrary that $\hat{u}_B^m \leq u_B^m$ along some subsequence of m . (All references that follow are to this subsequence.) Then

$$\begin{aligned} \sigma_m &= \frac{\bar{\lambda}_A}{1 - \hat{\lambda}_B^m} = \frac{p[1 - F(\bar{u}_A)]}{1 - (1-p)[1 - F(\hat{u}_B^m)]} \geq \frac{p[1 - F(\bar{u}_A)]}{1 - (1-p)[1 - F(u_B^m)]} \\ &= \frac{\bar{\lambda}_A}{1 - \lambda_B^m}. \end{aligned} \tag{26}$$

Recall from (21), Step 2, that $\frac{\lambda_B^m}{1 - \bar{\lambda}_A} \rightarrow \frac{v}{1-v}$. Therefore $\lambda_B^m \rightarrow \bar{\lambda}_B$, where $\bar{\lambda}_B \equiv \frac{v}{1-v} (1 - \bar{\lambda}_A)$. Recall from (16) that $\bar{\lambda}_A > v$, so that $\bar{\lambda}_B < v$ and in particular $\bar{\lambda}_B < \bar{\lambda}_A$. Because $p \leq \frac{1}{2}$, so is $\bar{\lambda}_A$,

and these last assertions permit us to conclude that $\bar{\lambda}_A (1 - \bar{\lambda}_A) > \bar{\lambda}_B (1 - \bar{\lambda}_B)$, or equivalently, that

$$\frac{\bar{\lambda}_A}{1 - \bar{\lambda}_B} > \frac{\bar{\lambda}_B}{1 - \bar{\lambda}_A}.$$

Using this information in (26) and recalling that $\lambda_B^m \rightarrow \bar{\lambda}_B$, we may conclude that

$$\liminf_{m \rightarrow \infty} \sigma_m \geq \frac{\bar{\lambda}_A}{1 - \bar{\lambda}_B} > \frac{\bar{\lambda}_B}{1 - \bar{\lambda}_A} = \frac{v}{1 - v},$$

where the last equality is from (21). It follows from (25) that $\hat{u}_B^m \rightarrow \infty$. But this contradicts our supposition that $\hat{u}_B^m \leq u_B^m$ (that along a subsequence) because the latter is bounded; see (21) of Step 2. \square

Proof of Proposition 2. Consider any sequence $\{n, q\}$ as described in the statement of the proposition. Choose some cutoff \bar{u}_A that satisfies (16). By Lemma 1, there is an integer N such that for all $n \geq N$, $\hat{u}_B^n > u_B^n > \bar{u}_A$. Define, for each $n \geq N$ and each $u_A \in (0, \bar{u}_A]$, $\psi^n(u_A)$ as the *difference* between B 's equilibrium response to u_A and the value of u_B to which u_A is an equilibrium response. By Lemma 1 and Observation 3, ψ^n is well defined and continuous on this interval. Using Observation 3 yet again, it is easy to see that (for each n) $\psi^n(u_A) < 0$ for small values of u_A , while the statement of Lemma 1 assures us that $\psi^n(\bar{u}_A) > 0$. Therefore for each n , there is $\tilde{u}_A^n \in (0, \bar{u}_A)$ such that $\psi^n(\tilde{u}_A^n) = 0$. If we define \tilde{u}_B^n to be the equilibrium response to \tilde{u}_A^n , it is trivial to see that $(\tilde{u}_A^n, \tilde{u}_B^n)$ constitutes an equilibrium.

Finally, note that

$$\tilde{u}_A^n < \bar{u}_A < u_B^n < \hat{u}_B^n < \bar{u}_B^n,$$

where the second and third inequalities are a consequence of Lemma 1, and the last inequality comes from the fact that the equilibrium response function is decreasing (Observation 2). This means that $(\tilde{u}_A^n, \tilde{u}_B^n)$ is a minority equilibrium. \square

Proof of Proposition 3. Suppose on the contrary that a minority equilibrium (u_A^n, u_B^n) exists along some subsequence of n (all references that follow are to this subsequence). Then $\lim_{n \rightarrow \infty} (u_A^n, u_B^n)$ is either (∞, ∞) , $(0, \infty)$ or a pair of strictly positive but finite numbers (u_A^*, u_B^*) . To prove that our supposition is wrong, we show that none of these limits can apply.

Assume $(u_A^n, u_B^n) \rightarrow (\infty, \infty)$. Then $\lambda_A^n \rightarrow 0$ and $\lambda_B^n \rightarrow 0$. This implies that $\pi^n \rightarrow 0$ and $\sigma^n \rightarrow 0$. But this implies, by Eqs. (5) and (6) and using SLLN, that $(u_A^n, u_B^n) \rightarrow (0, 0)$, a contradiction.

Assume $(u_A^n, u_B^n) \rightarrow (0, \infty)$. Then $\lambda_A^n \rightarrow p$ and $\lambda_B^n \rightarrow 0$, so that $\sigma^n \rightarrow p < v < \frac{q}{m-1}$. But using (6) and SLLN, this implies that $u_B^n \rightarrow 0$, a contradiction.

Assume $(u_A^n, u_B^n) \rightarrow (u_A^*, u_B^*)$, where both u_A^* and u_B^* are strictly positive and finite. Using SLLN and Eqs. (5) and (6), it follows that π^n and σ^n must both converge to $\frac{q}{m-1}$. This means that $\lambda_A^n \rightarrow \lambda_A^*$ and $\lambda_B^n \rightarrow \lambda_B^*$ such that

$$\frac{\lambda_B^*}{1 - \lambda_A^*} = \frac{\lambda_A^*}{1 - \lambda_B^*}.$$

This equality holds only if $\lambda_A^* = \lambda_B^*$, or if $\lambda_A^* = 1 - \lambda_B^*$. Suppose the former is true. Then $\pi^n \rightarrow \pi^*$ where

$$\pi^* = \frac{\lambda_B^*}{1 - \lambda_A^*} < \frac{v}{1 - v} \simeq \frac{q}{m - 1}.$$

But the above inequality implies, by (5) and SLLN, that $u_A^n \rightarrow 0$, a contradiction. Suppose next that $\lambda_A^* = 1 - \lambda_B^*$. But $1 - \lambda_B^* > p > \lambda_A^*$, a contradiction. \square

Proof of Proposition 4. Under unanimity, (5) and (6) reduce to

$$\frac{1}{1 + u_A} = (1 - \pi)^{n-1} \tag{27}$$

and

$$\frac{1}{1 + u_B} = (1 - \sigma)^{n-1}. \tag{28}$$

For any given n and $k = A, B$, define $y_k \equiv (1 + u_k)^{1/(n-1)}$. Then $y_k \geq 1$, and (27) and (28) may be rewritten as

$$1 - \pi = \frac{1}{y_A} \tag{29}$$

and

$$1 - \sigma = \frac{1}{y_B}. \tag{30}$$

Recalling that $\pi = \lambda_B/(1 - \lambda_A)$ and $\sigma = \lambda_A/(1 - \lambda_B)$, we may use (29) and (30) to solve explicitly for λ_A and λ_B . Doing so and writing out λ_k for $k = A, B$, we see that

$$\lambda_A = p[1 - F(u_A)] = \frac{y_B - 1}{y_A + y_B - 1}, \tag{31}$$

while

$$\lambda_B = (1 - p)[1 - F(u_B)] = \frac{y_A - 1}{y_A + y_B - 1}. \tag{32}$$

By multiplying both sides of (31) by $1 - F(u_B)$ and both sides of (32) by $1 - F(u_A)$ and using the fact that $p < 1 - p$, we may conclude that

$$[1 - F(u_B)] \left[(1 + u_B)^{1/(n-1)} - 1 \right] < [1 - F(u_A)] \left[(1 + u_A)^{1/(n-1)} - 1 \right]. \tag{33}$$

We will now prove that $u_A > u_B$. Given (33), it will suffice to prove that

$$[1 - F(x)] \left[(1 + x)^{1/(n-1)} - 1 \right]$$

is nondecreasing in x . This, in turn, is implied by the stronger observation that

$$\frac{d}{dx} [1 - F(x)] \left[(1 + x)^{1/(n-1)} - 1 \right] \geq 0$$

for every $x > 0$, or equivalently, that

$$\frac{f(x)}{1 - F(x)} \leq \frac{\theta(1+x)^{\theta-1}}{(1+x)^\theta - 1}, \tag{34}$$

where $\theta \equiv \frac{1}{n-1} \in (0, 1]$.

To this end, we demonstrate that for all $x > 0$ and $\theta \in (0, 1]$,

$$\frac{\theta(1+x)^{\theta-1}}{(1+x)^\theta - 1} \geq \frac{1}{(1+x) \ln(1+x)}. \tag{35}$$

To establish (35), note that for fixed $x > 0$, $h(\theta) \equiv (1+x)^\theta$ is differentiable and convex in x . By a standard property of differentiable convex functions, $h(\theta_1) - h(\theta_2) \leq h'(\theta_1)(\theta_1 - \theta_2)$ for all θ_1 and θ_2 . Applying this inequality to the case $\theta_1 = \theta$ and $\theta_2 = 0$, we may conclude that

$$h(\theta) - h(0) = (1+x)^\theta - 1 \leq h'(\theta)\theta = (1+x)^\theta \ln(1+x)\theta$$

and a quick rearrangement of this inequality produces (35).

To complete the proof, combine (7) and (35) to obtain (34). \square

Proof of Proposition 6. Recall the conditions describing equilibrium cutoffs:

$$\frac{1}{1 + u_A} = \sum_{k=0}^q \binom{m-1}{k} \pi^k (1 - \pi)^{m-1-k}$$

and

$$\frac{1}{1 + u_B} = \sum_{k=0}^q \binom{m-1}{k} \sigma^k (1 - \sigma)^{m-1-k}.$$

For each integer n (with associated m and q) and every $u \geq 0$, define a function $h(u, n)$ by the condition that

$$\sum_{k=0}^q \binom{m-1}{k} h(u, n)^k (1 - h(u, n))^{m-1-k} \equiv \frac{1}{1 + u}.$$

Note that h is well-defined for each (u, n) . With this in hand, we may rewrite the equilibrium conditions more succinctly as

$$\frac{\lambda_B^n}{1 - \lambda_A^n} = \pi^n = h(u_A^n, n) \equiv \alpha^n \tag{36}$$

and

$$\frac{\lambda_A^n}{1 - \lambda_B^n} = \sigma^n = h(u_B^n, n) \equiv \beta^n, \tag{37}$$

where we are now starting to index all endogenous variables by n in order to prepare for sequences of equilibria. Solving these two equations for λ_A^n and λ_B^n , we see that

$$\lambda_A^n = p[1 - F(u_A^n)] = \frac{\beta^n(1 - \alpha^n)}{1 - \alpha^n \beta^n} \tag{38}$$

and

$$\lambda_B^n = (1 - p)[1 - F(u_B^n)] = \frac{\alpha^n(1 - \beta^n)}{1 - \alpha^n\beta^n}. \tag{39}$$

We now study various limits of equilibrium cutoff sequences. We will denote the limits in all cases by (u_A^*, u_B^*) . The following lemma summarizes simple properties of h and will be used throughout.

Lemma 2. (1) For every n , h is strictly increasing in u , with $h(0, n) = 0$ and $h(u, n) \rightarrow 1$ as $n \rightarrow \infty$.

(2) If u^n converges to u with $0 < u < \infty$, then $\lim_{n \rightarrow \infty} h(u^n, n) = v/(1 - v)$.

(3) If u^n converges to 0 then $\limsup_{n \rightarrow \infty} h(u^n, n) \leq v/(1 - v)$.

(4) If $u^n \rightarrow \infty$, then $\liminf_{n \rightarrow \infty} h(u^n, n) \geq v/(1 - v)$.

The proof of this lemma follows from routine computations and the use of the law of large numbers, and is omitted.

Now we prove part (1) of the proposition. First, we claim that u_A^* and u_B^* are finite. For suppose, say, that $u_A^* = \infty$ (the argument in the other case is identical). It follows from (38) that either α^n has a limit point at 1, or that β^n has a zero limit point. The latter possibility is ruled out by Lemma 2, because $u_B^* > 0$ by assumption. It follows that $\limsup_{n \rightarrow \infty} \alpha^n = 1$, but then Lemma 2 assures us that $u_B^* = \infty$ as well.

The first of the two conclusions in the preceding sentence implies that $\limsup_{n \rightarrow \infty} \lambda_B^n = 1$ (use (37)), but the second conclusion implies that $\lim_{n \rightarrow \infty} \lambda_B^n = 0$ (use (39)). These two implications contradict each other.

So $0 \ll (u_A^*, u_B^*) \ll \infty$, but we know then from Lemma 2 that $(\alpha^n, \beta^n) \rightarrow (v, v)$ as $n \rightarrow \infty$. Simple computation using (38) and (39) then yields (8). It should be noted that this limit (which is unique in the class of strictly positive limits) has $u_A^* < u_B^*$; that is, it is a “limit” minority equilibrium.

Next, we prove part (2); the proof of part (3) is completely analogous. Suppose, then, that $u_A^* = 0$. We first prove the sufficiency of the restriction on p . To this end, assume that $u_B^* = \infty$. Consider some subsequence in which α^n and β^n converge (to some α^* and β^*). Then (38) implies that

$$\frac{\beta^*(1 - \alpha^*)}{1 - \alpha^*\beta^*} = p. \tag{40}$$

while at the same time, (39) implies that

$$\frac{\alpha^*(1 - \beta^*)}{1 - \alpha^*\beta^*} = 0, \tag{41}$$

(41) implies either that $\alpha^* = 0$ or that $\beta^* = 1$. But the latter cannot happen, for then (40) cannot be satisfied (note that the LHS of (40) is well-defined even when $\beta^* = 1$, because $\alpha^* < 1$ by Lemma 2). So it must be that $\alpha^* = 0$. But then (40) implies that $p = \beta^*$. Lemma 2 tells us that $\beta^* \geq v/(1 - v)$, so that $p \geq v/(1 - v)$.

Conversely, suppose that $u_B^* < \infty$. Again, consider some subsequence in which α^n and β^n converge to some α^* and β^* . Therefore (38) implies that

$$\frac{\beta^*(1 - \alpha^*)}{1 - \alpha^*\beta^*} = p. \tag{42}$$

while (39) implies that

$$\frac{\alpha^*(1 - \beta^*)}{1 - \alpha^*\beta^*} = (1 - p)[1 - F(u_B^*)]. \tag{43}$$

We can eliminate α^* from this system. We also note that by Lemma 2, β^* must equal $v/(1 - v)$. Using these observations along with some routine computation, we obtain precisely (9).

We also know that $F(u_B^*) < 1$. Using this information in (9), we may conclude that $p < v/(1 - v)$.

Finally, we establish part (4). Assume, to the contrary, there exists no sequence of equilibria whose limit is given by the first configuration. By parts (2) and (3) of the proposition, the limit of any sequence of minority equilibria has either $u_A^* = 0$ or $u_A^* > u_B^*$. To reach a contradiction, pick any $u_A > 0$ satisfying (16). By Lemma 1, there exists an integer N such that for all $n \geq N$, there exists a minority equilibrium (u_A^n, u_B^n) with $u_A^n > u_A$. From Proposition 1 it follows that for any $p < \frac{1}{2}$ and for any n , there does not exist a pair of numbers (u, v) that solve the equilibrium conditions (5) and (6). We therefore conclude that for all $n \geq N$, there exists a minority equilibrium (u_A^n, u_B^n) with $0 < u_A < u_A^n < u_B^n$, in contradiction to our initial assumption.

Suppose next that there exists no sequence of equilibria whose limit is given by the second configuration. Then by parts (1) and (3) of the proposition, the limit of any minority equilibrium must satisfy that $u_A^* \geq v > 0$. Let $\varepsilon \in (0, v)$. By Lemma 1, there exists a finite $N > 0$ such that for all $n \geq N$ there exists a minority equilibrium (u_A^n, u_B^n) with $u_A^n < \varepsilon$. But this means that the limit of any such sequence cannot satisfy that $u_A^* \geq v$, a contradiction.

Finally, assume there exists no sequence of equilibria whose limit is given by the third configuration. This implies, by (1) and (2), that the limit of any sequence of equilibrium cutoffs has $u_A^* < u_B^*$. But this contradicts Proposition 1, which states that for every n there exists an equilibrium with $u_A^n > u_B^n$. \square

Proof of Proposition 7. The proofs of (1) and (2) are given in the discussion following the statement of the proposition in the text. We now proceed to prove (3). Assume that $q < \frac{n-1}{2}$ (when $q = \frac{n-1}{2}$ the probability of disagreement is zero). Note that the probability of disagreement is equal to $\Pr(|A| > q, |B| > q)$, where $|\cdot|$ stands for cardinality. Because

$$\Pr(|A| > q, |B| > q) \leq \min\{\Pr(|A| > q), \Pr(|B| > q)\},$$

it suffices to show that $\Pr(A > q)$ and $\Pr(B > q)$ cannot both converge to one along some subsequence of n .

Suppose, on the contrary, that $\Pr(A > q)$ and $\Pr(B > q)$ do converge to one along some subsequence of n (retain notation). The proof proceeds in two steps. In the first step we show that for large n both λ_A and λ_B are strictly above v . Moreover, if either λ_A or λ_B converges to v , then it converges at a rate slower than $\frac{1}{\sqrt{n}}$. In the second step we show that this implies that the equilibrium cutoffs, u_A and u_B , must be growing to infinity, in contradiction to step 1.

Step 1: $\lim_{n \rightarrow \infty} \frac{(\lambda_A - v)\sqrt{n}}{\sqrt{\lambda_A(1 - \lambda_A)}} = \infty$ and $\lim_{n \rightarrow \infty} \frac{(\lambda_B - v)\sqrt{n}}{\sqrt{\lambda_B(1 - \lambda_B)}} = \infty$.

We prove $\lim_{n \rightarrow \infty} \frac{|\lambda_A - v|\sqrt{n}}{\sqrt{\lambda_A(1 - \lambda_A)}} = \infty$; similar arguments hold for λ_B .

Assume to the contrary that there exists a subsequence for which $\lim_{n \rightarrow \infty} \frac{(\lambda_A^{k_n} - v)\sqrt{n}}{\sqrt{\lambda_A(1 - \lambda_A)}} = c$, where $-\infty \leq c < \infty$.

Let X_n denote the number of A announcements (i.e., $|A|$). By the Berry-Esséen Theorem (see, for example, [9, Chapter XVI.5, Theorem 1]), for some $\varepsilon < \Phi(-c)$, there exists an N such that for $n > N$:

$$\Pr(X_n > q) = \Pr\left(\frac{X_n - n\lambda_A^{k_n}}{\sqrt{n\lambda_A^{k_n}(1-\lambda_A^{k_n})}} > \frac{-(\lambda_A^{k_n} - v)\sqrt{n}}{\sqrt{\lambda_A^{k_n}(1-\lambda_A^{k_n})}}\right) < 1 - \Phi(-c) + \varepsilon < 1$$

and this contradicts our premise that $\lim_{n \rightarrow \infty} \Pr(|A| > q) = 1$.

Recalling that $\pi = \frac{\lambda_B}{1-\lambda_A}$ and $\sigma = \frac{\lambda_A}{1-\lambda_B}$, it follows from step 1 that $\lim_{n \rightarrow \infty} \frac{(\pi - \frac{v}{1-v})\sqrt{n}}{\sqrt{\pi(1-\pi)}} = \infty$ and $\lim_{n \rightarrow \infty} \frac{(\sigma - \frac{v}{1-v})\sqrt{n}}{\sqrt{\sigma(1-\sigma)}} = \infty$.

Step 2: If $\lim_{m \rightarrow \infty} \frac{(\pi - \frac{v}{1-v})\sqrt{m-1}}{\sqrt{\pi(1-\pi)}} = \infty$ and $\lim_{m \rightarrow \infty} \frac{(\sigma - \frac{v}{1-v})\sqrt{m-1}}{\sqrt{\sigma(1-\sigma)}} = \infty$, then $u_A \rightarrow \infty$ and $u_B \rightarrow \infty$.

As in step 1 we provide a proof for u_A and similar arguments follow for u_B .

Let Y_n be the sum of successes from a binomial distribution with probability of success π and with $m - 1$ draws. Then

$$\begin{aligned} \sum_{k=0}^q \binom{m-1}{k} \pi^k (1-\pi)^{m-1-k} &= \Pr(Y_n \leq q) \leq \Pr(|Y_n - (m-1)\pi| \geq (m-1)\pi - q) \\ &< \frac{\text{Var}(Y_n)}{((m-1)\pi - q)^2} = \frac{1}{\left(\frac{(\pi - \frac{q}{m-1})\sqrt{m-1}}{\sqrt{\pi(1-\pi)}}\right)^2} \rightarrow 0, \end{aligned}$$

where the last inequality is by Chebyshev’s inequality and the limit follows from the premise. Therefore, by (5) it must be that $u_A \rightarrow \infty$. This implies that $\lambda_A \rightarrow 0$, in contradiction to step 1. □

Proof of Observation 5. In place of the variable u , define a variable u^a for the A types by

$$u^a \equiv \alpha \frac{v - v'}{v'}$$

and a corresponding variable u^b for the B types by

$$u^b \equiv (1 - \alpha) \frac{v - v'}{v'}$$

Nothing changes in our description of the equilibrium conditions (5) and (6), except that a Z-type defines her threshold u_Z using the variable u^z . Notice that the cdfs of u^a and u^b are now different, but that

$$F^a(u^a) = F\left(\frac{u^a}{2\alpha}\right) \text{ and } F^b(u^b) = F\left(\frac{u^b}{2[1-\alpha]}\right). \tag{44}$$

Now, suppose that along some sequence α converging to 1, λ_B does not converge to zero. Then, because $\lambda_B = (1 - p)[1 - F^b(u_B)]$, $F^b(u_B)$ fails to converge to 1, which means (using (44)) that u_B must converge to zero. Using (6), we must conclude that

$$\sigma = \frac{\lambda_A}{1 - \lambda_B}$$

converges to 0. But this must imply in turn that λ_A converges to 0, or that $F^a(u_A)$ converges to 1. Using (44) again, we must conclude that $u_A \rightarrow \infty$, so by (5),

$$\pi = \frac{\lambda_B}{1 - \lambda_A}$$

converges to 1. With λ_A converging to 0 and λ_B bounded above by $1 - p = \frac{1}{2}$, this is an impossibility.

So we have shown that λ_B converges to zero. Because λ_A is bounded above by $p = \frac{1}{2}$, this means that

$$\pi = \frac{\lambda_B}{1 - \lambda_A}$$

converges to zero as well. An inspection of (5) now shows that u_A must converge to 0. Using (44), it follows that $F^a(u_A)$ also converges to 0, which proves that $\lambda_A = p[1 - F^a(u_A)]$ converges to $p = \frac{1}{2}$. \square

Proof of Observation 6. To prove part (1), define $\delta \equiv 1/(n - 1 - 2q)$, and rewrite (12) as

$$(1 + w_B^\delta)[1 - H(w_B)] = 1/(1 - p). \tag{45}$$

Notice that when $w_B = 1$, the LHS of (45) equals 2, while the RHS is strictly smaller than 2 (because $p < \frac{1}{2}$).

Now suppose that there is some w such that the LHS of (45), evaluated at $w_B = w$, is strictly less than $1/(1 - p)$. In this case, consider some intersection $x = w_B$ of the function $(1 + x^\delta)[1 - H(x)]$ with the value $1/(1 - p)$, along with the value $w_A = 1$. It can be verified that such an intersection constitutes a semi-corner minority equilibrium.

It remains to show that the condition in the first line in the previous paragraph is satisfied for all (n, q) large enough. To this end, fix some w such that $1 - H(w) < \frac{1}{2}(1 - p)$. Now take (n, q) to infinity and notice that $\delta \rightarrow 0$. Therefore w^δ converges to 1. It follows that for large (n, q) ,

$$(1 + w^\delta)[1 - H(w)] < 1/(1 - p)$$

and we are done.

Note that part (2) is trivially true for corner minority equilibria. To prove part (2) for semi-corners, note that the probability that the minority outcome is implemented is given by

$$\Pr(|A| \geq m) = \sum_{k=m}^n \binom{n}{m} [p + (1 - p)H(w_B)]^k [(1 - p)(1 - H(w_B))]^{n-k}.$$

Similarly,

$$\Pr(|B| \geq m) = \sum_{k=m}^n \binom{n}{m} [(1 - p)(1 - H(w_B))]^k [p + (1 - p)H(w_B)]^{n-k}.$$

Thus, $\Pr(|A| \geq m) > \Pr(|B| \geq m)$ if and only if $(1 - p)(1 - H(w_B)) < p + (1 - p)H(w_B)$, which may be rewritten as

$$\frac{1}{2(1 - p)} > 1 - H(w_B). \tag{46}$$

Now (45) tells us that

$$1 - H(w_B) = \frac{1}{(1 - p)(1 + w_B^\delta)},$$

where $w_B > 1$. Hence, $(1 - p)(1 + w_B^\delta) > 2(1 - p)$, which implies (46). \square

Proof of Observation 7. Let w_B^* be the solution to the following equation:

$$p + (1 - p)H(w_B^*) = (1 - p)[1 - H(w_B^*)].$$

Notice that w_B^* is well-defined and greater than 1, as long as $p < \frac{1}{2}$. We now proceed in two steps.

Step 1: There exists a sequence of semi-corner minority equilibria that converges to $(1, w_B^*)$. To see this, note that when $w_B = w_B^*$ the RHS of (13) is smaller than the LHS. For any $\varepsilon > 0$, set $w_B = w_B^* + \varepsilon$. Because $\frac{p+(1-p)H(w_B^*+\varepsilon)}{(1-p)[1-H(w_B^*+\varepsilon)]} > 1$, there exists $N(\varepsilon) < \infty$ such that for all $n \geq N(\varepsilon)$, the LHS of (13) is strictly greater than its RHS. It follows that for all $n \geq N(\varepsilon)$, there exists an equilibrium $(1, w_B^n)$ where $w_B^n \in (w_B^*, w_B^* + \varepsilon)$.

Step 2: By Step 1, as $n \rightarrow \infty$, the probabilities with which a random voter votes for A or for B (along the above sequence of semi-corner minority equilibria) both converge to $\frac{1}{2}$. In particular, there exists an N above which these probabilities are bounded below by $\bar{v} > v$ and above by $1 - \bar{v}$. The probability of disagreement is equal to $1 - \Pr(|A| \geq m) - \Pr(|B| \geq m)$. We now show that $\Pr(|A| \geq m)$ goes to zero as $n \rightarrow \infty$. By essentially the same argument, $\Pr(|B| \geq m)$ also goes to zero as $n \rightarrow \infty$.

Recall that

$$\Pr(|A| \geq m) = \sum_{k=m}^n \binom{n}{m} [p + (1 - p)H(w_B)]^k [(1 - p)(1 - H(w_B))]^{n-k}.$$

Note that $|\frac{m}{n} - (1 - v)| < \frac{1}{n}$. Because $1 - \bar{v} < 1 - v$ it follows that for large enough n ,

$$1 - \bar{v} < \frac{m}{n} - \eta \tag{47}$$

for some $\eta > 0$. By stochastic dominance,

$$\Pr(|A| \geq m) \leq \sum_{k=m}^n \binom{n}{m} (1 - \bar{v})^k (\bar{v})^{n-k}. \tag{48}$$

By inequality (47) and the SLLN, the RHS of (48) goes to zero. \square

Observation 8. Consider the model with a majority tie-breaking rule. All symmetric equilibria in this model are interior.

Proof. We proceed in three steps.

Step 1: No side can use an infinite cutoff in equilibrium. Suppose that side A does. Then note that no matter what rule side B follows, $\tau + \tau' > 0$. This is because the sum of probabilities $\tau + \tau'$ is greater than the probability that both sides have exactly zero votes, which in turn, is at least as high as the probability that all individuals but one are A types. Since the latter probability is positive we obtain the desired inequality.

In order for an A -type to declare neutrality in equilibrium, his u value must satisfy $(\tau + \tau')u < P^+$. But this inequality cannot hold for an infinite u because we have just shown that $\tau + \tau' > 0$, a contradiction. Hence, equilibrium cutoffs of both sides are bounded.

Step 2: $P^+ > 0$. To prove this, fix some person, say of type A , and simply take the event in which exactly q compatriots are of type A (apart from the special individual) and the rest are of type B , and all value realizations are above the cutoffs. Because cutoffs are bounded, the probability of this event is strictly positive. But this event is contained within the one covered by P^+ . So $P^+ > 0$.

Step 3: In any equilibrium, cutoffs are strictly positive. To see this, note by step 2 that $P^+ > 0$. Now take u very small; the inequality $(\tau + \tau')u \geq P^+$ cannot hold. \square

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